

Challenges for Machine Learning in Computational Sustainability

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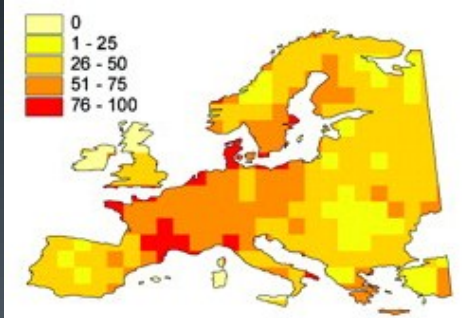
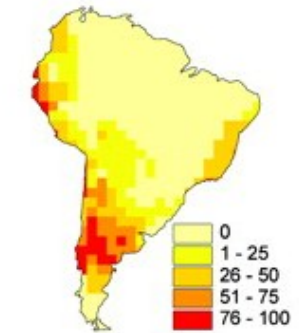
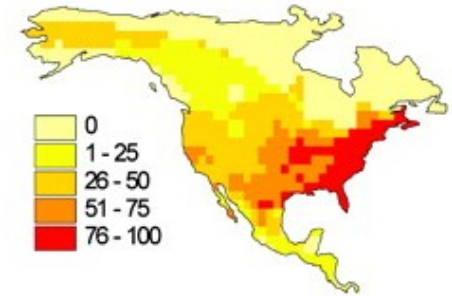


NIPS 2012



Sustainable Management of the Earth's Ecosystems

- The Earth's Ecosystems are complex
- We have failed to manage them in a sustainable way
 - Example:
 - Species extinction rate of mammals \approx 10-100 times historical rates
 - Mammalian populations are dropping rapidly worldwide



Ceballos & Erhlich, 2002

% mammal population lost

Why?

1. We did not think about ecosystems as a management or control problem
2. Our knowledge of function and structure is inadequate
3. Optimal management requires spatial planning over horizons of 100+ years

Computer Science can help!

1. We did not think about ecosystems as a management or control problem

2. Our knowledge of function and structure is inadequate

3. Optimal management requires spatial planning over horizons of 100+ years

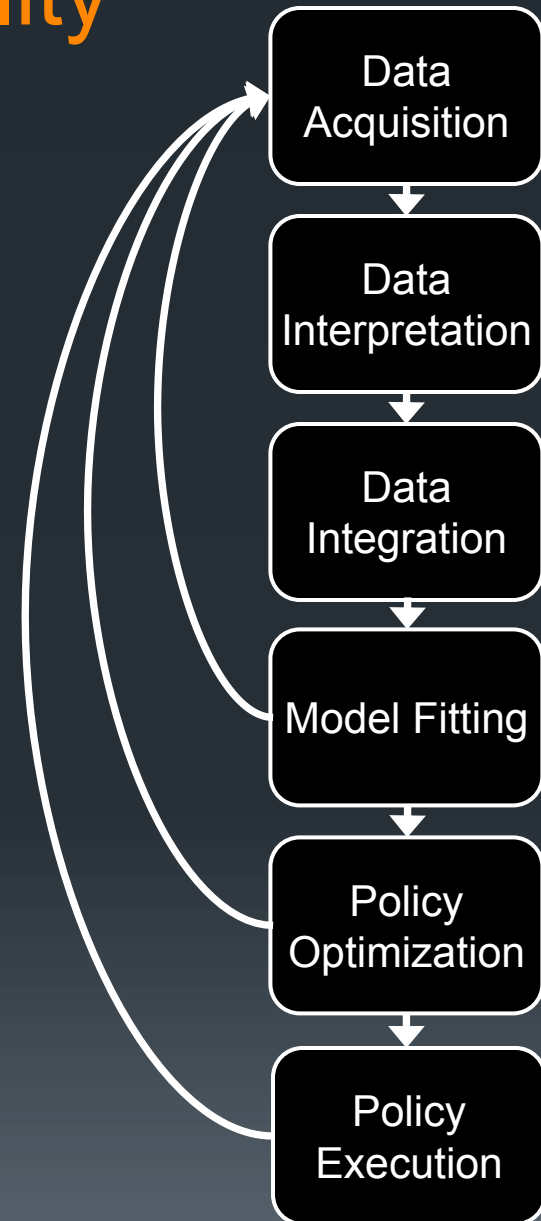
Sensors

Machine Learning

Optimization

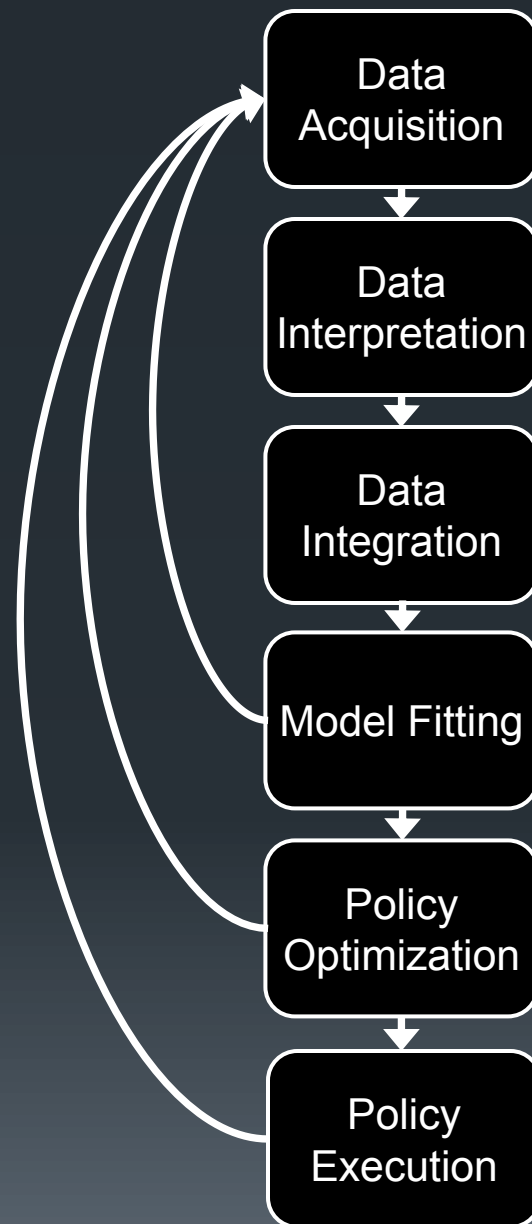
Computational Sustainability

- The study of computational methods that can contribute to the sustainable management of the earth's ecosystems
- Data → Models → Policies



Outline

- Illustrative Research Challenges for each stage
- Drill down on three projects at Oregon State University
- Discussion: What are the distinctive aspects of computational sustainability problems?



Example Research Challenges

Data Acquisition

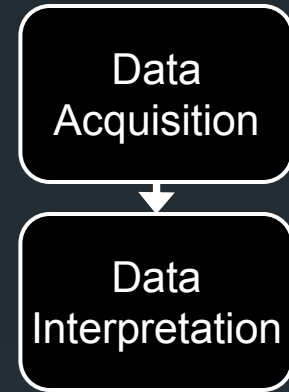
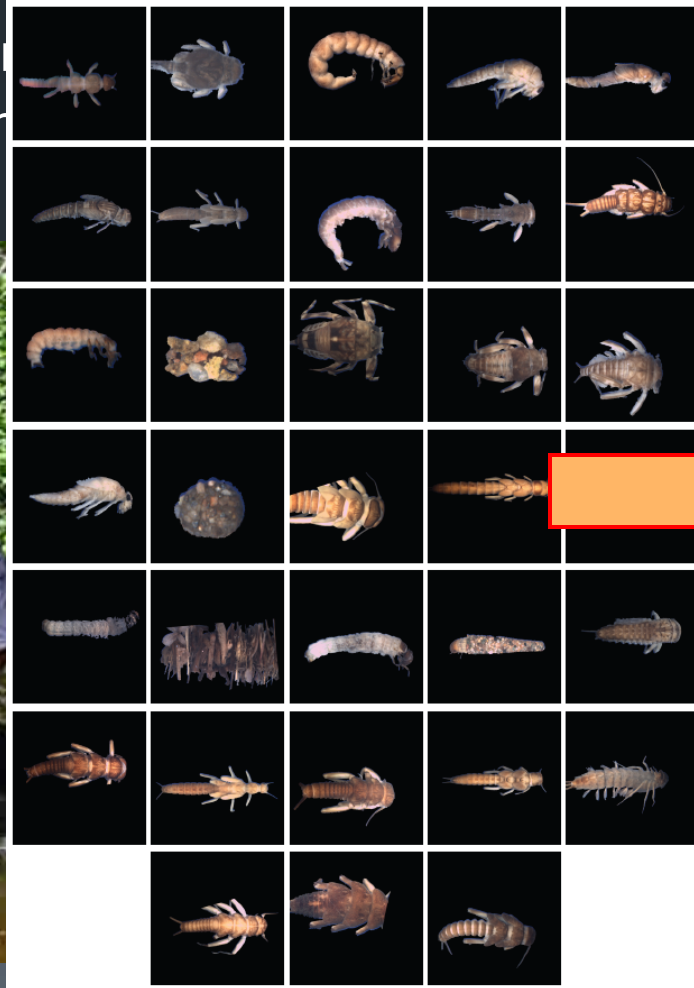
Data
Acquisition

- Africa is very poorly sensed
 - Only a few dozen weather stations reliably report data to WMO (blue points in map)
- Project TAHMO (tahmo.org)
 - TU-DELFT & Oregon State University
 - Design a complete meteorology sensor station at a cost of EUR 200
 - Deploy 20,000 such stations across Africa
 - Where should sensors be placed?
 - Accuracy of reconstructed fields for precipitation, temperature, relative humidity, wind, etc.
 - Robustness to sensor failure, station loss



Data Interpretation

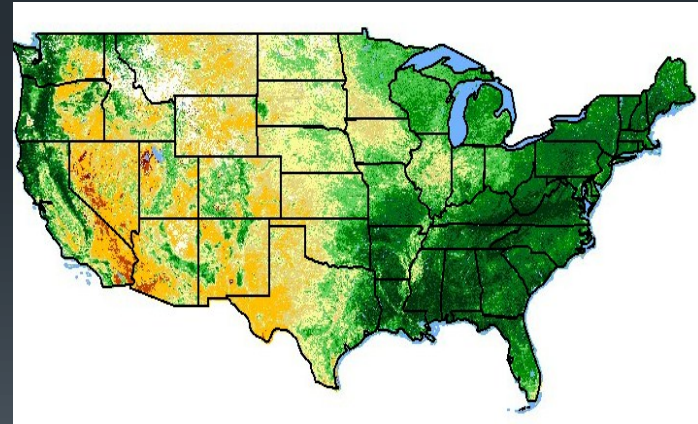
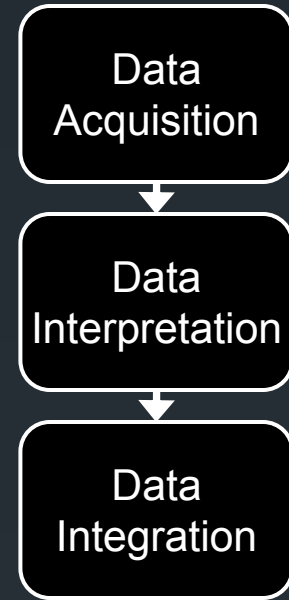
- Insect identification for population counting
- Raw data: image
- Interpreted data: Count
- Challenge: Fine-Grain



Species	Count
Limne	3
Taenm	15
Asiop	4
Epeor	25
Camel	19
Cla	12
Cerat	21

Data Integration

- Virtually all ecosystem prediction problems require integrating heterogeneous data sources
 - Landsat (30m; monthly)
 - land cover type
 - MODIS (500m; daily/weekly)
 - land cover type
 - Census (every 10 years)
 - human population density
 - Interpolated weather data (15 mins)
 - rain, snow, solar radiation, wind speed & direction, humidity
- Challenge:
 - Learn from heterogeneous data
 - without losing fine-grained information
 - without losing uncertainty in the data

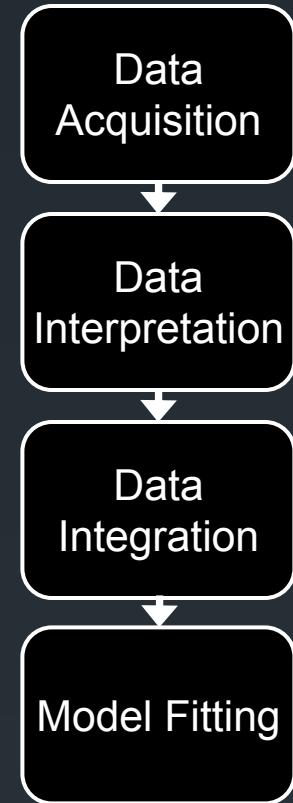


Landsat NDVI:

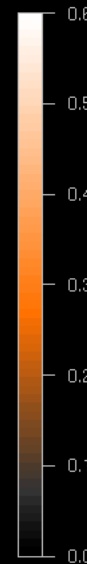
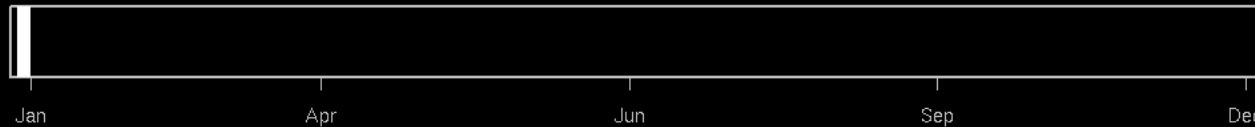
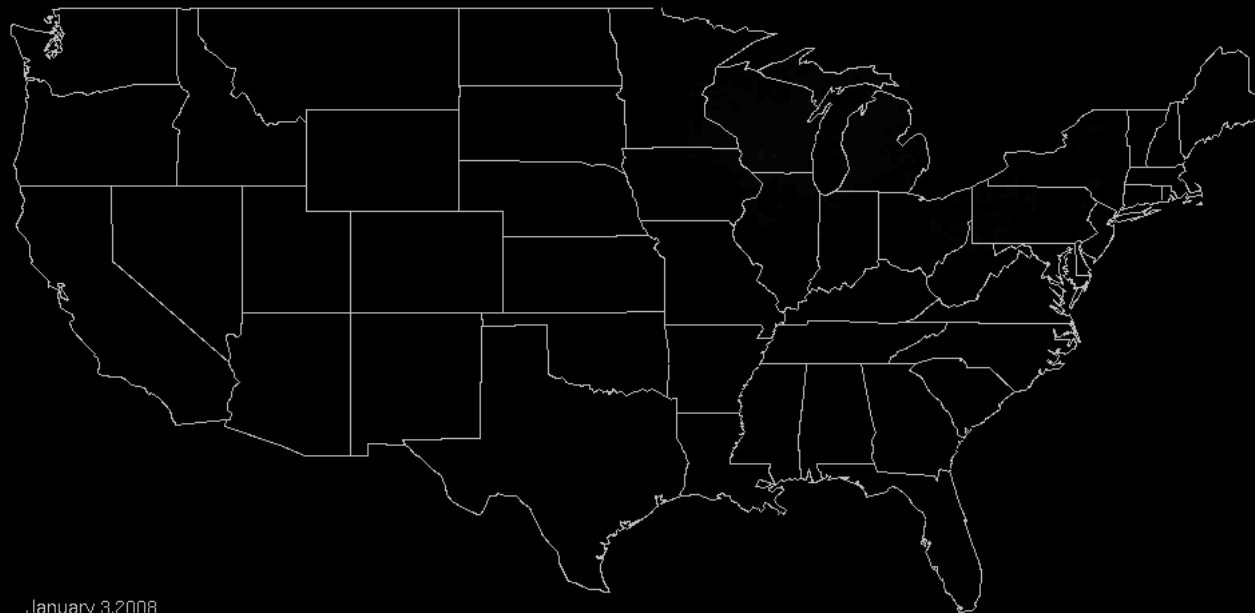
<http://ivm.cr.usgs.gov/viewer/>

Model Fitting

- Species Distribution Models
 - create a map of the distribution of a species
- Meta-Population Models
 - model a set of patches with local extinction and colonization
- Migration and Dispersal Models
 - model the trajectory and timing of movement
- Challenges
 - The variables of interest are all latent
 - Latent distribution of species
 - Latent dynamics
 - The data are very messy



State of the Art: STEM Model of Bird Species Distribution

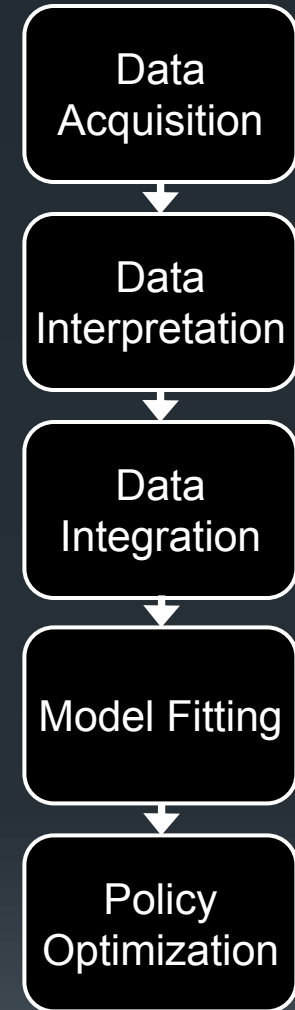


Indigo Bunting

Policy Optimization

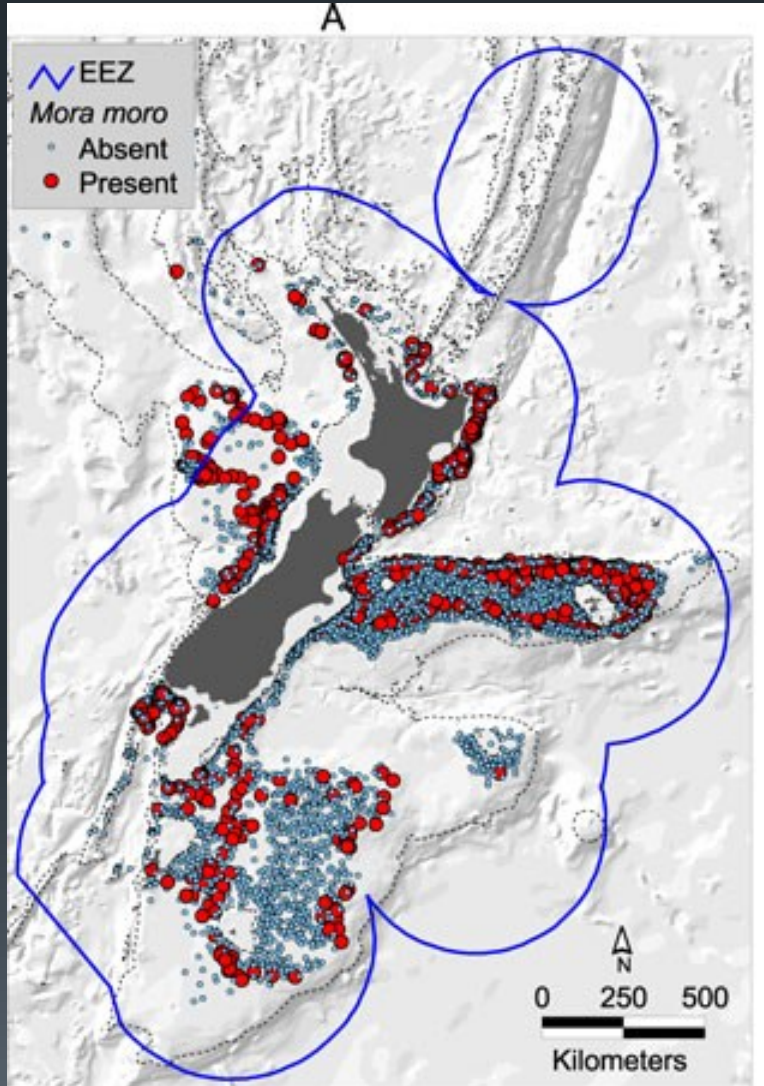
■ Challenges

- Long time horizons (100+ years)
- The system model is uncertain, so the optimization needs to be robust to this uncertainty
- The state of the system covers large spatial regions (scales exponentially in region size)
- System dynamics only available via simulation or sampling



State of the Art: Reserve Design from a Species Distribution Model

Observations



Data Acquisition

Data Interpretation

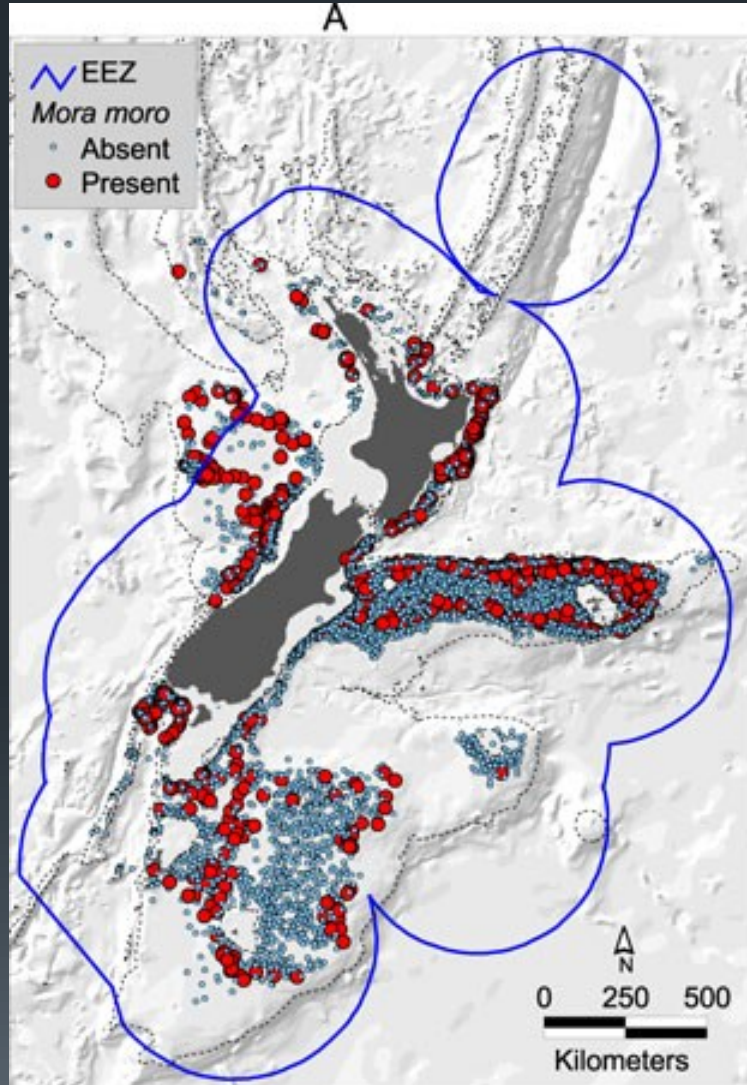
Data Integration

Model Fitting

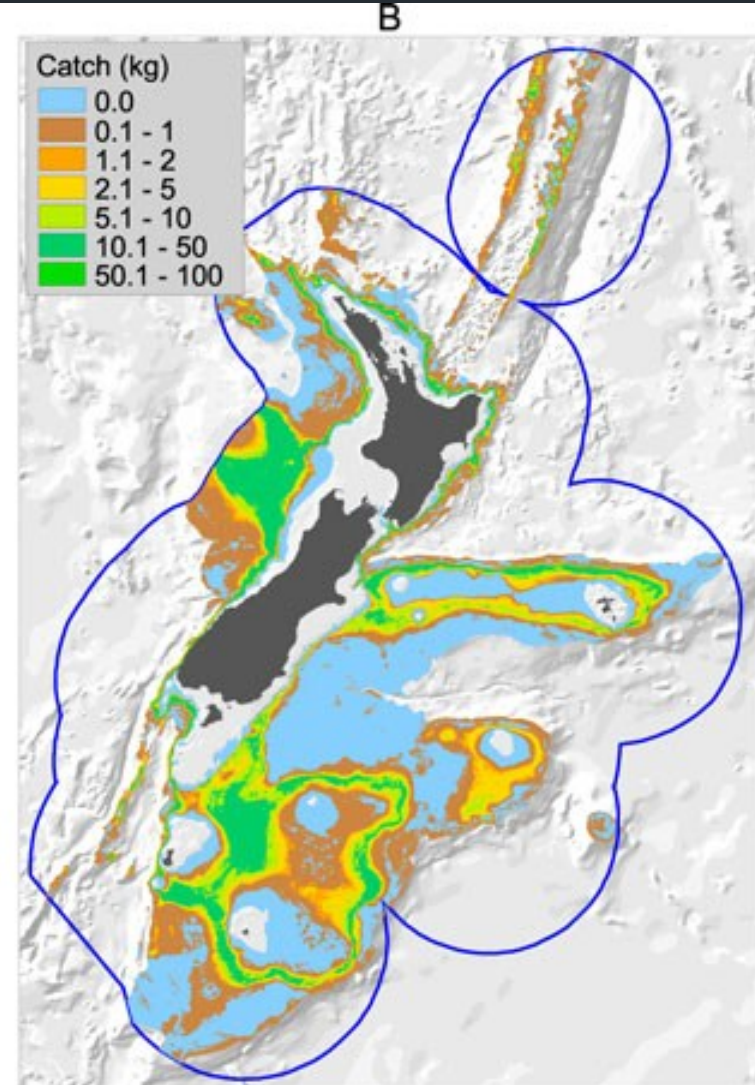
Policy Optimization

State of the Art: Reserve Design from a Species Distribution Model

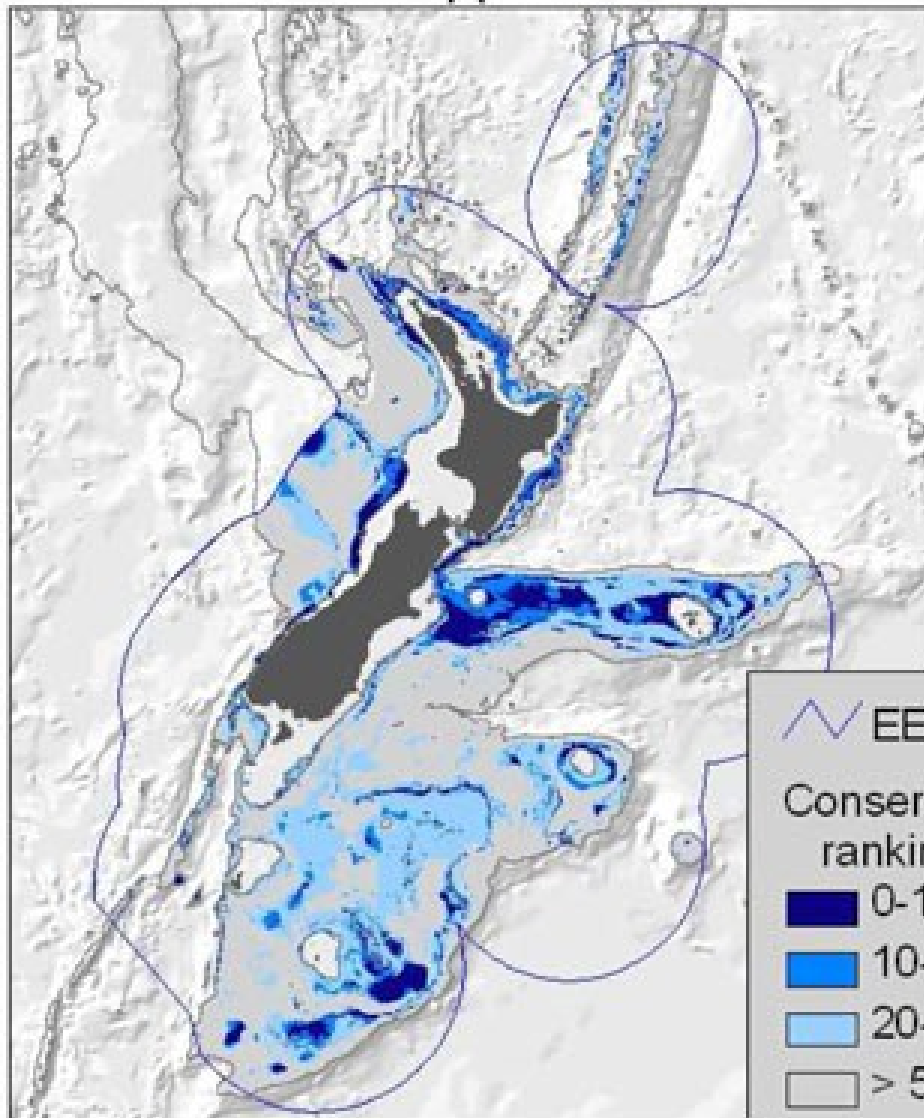
Observations



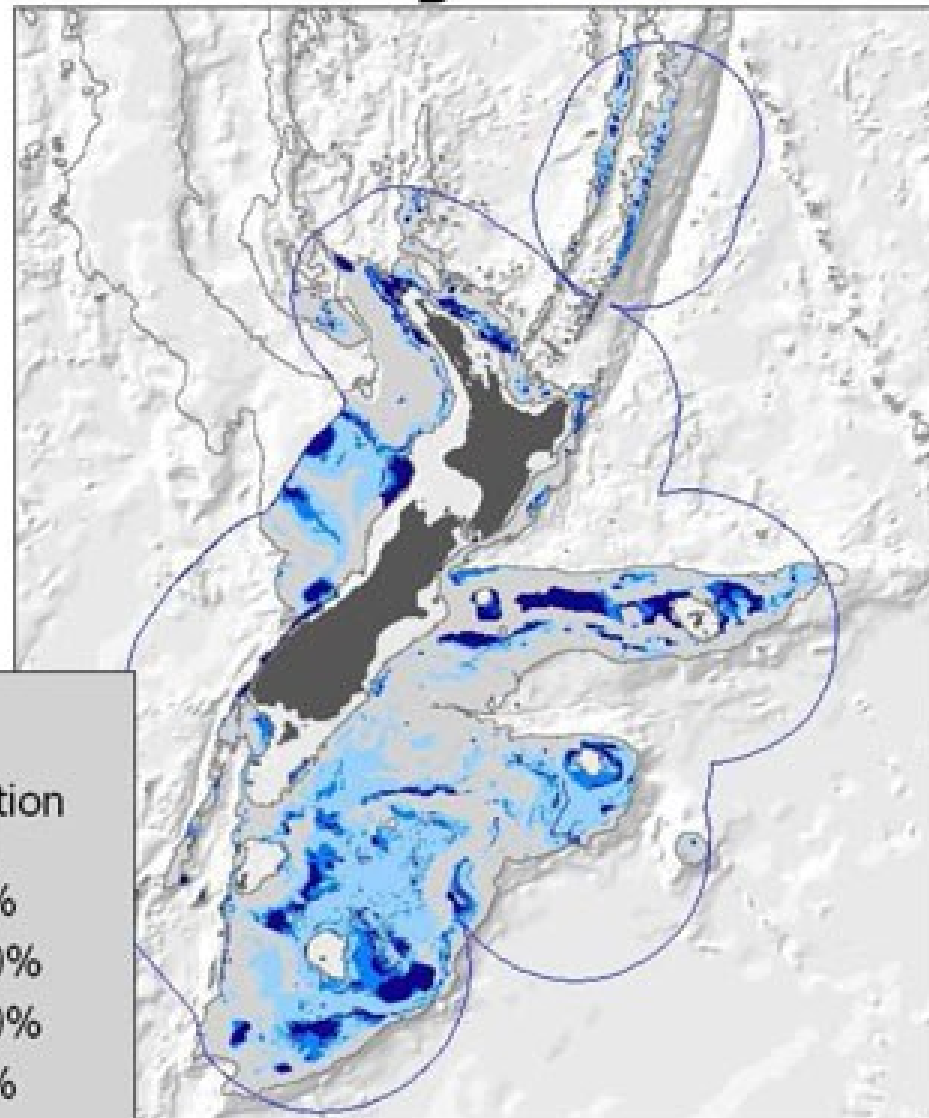
Fitted Model



A



B

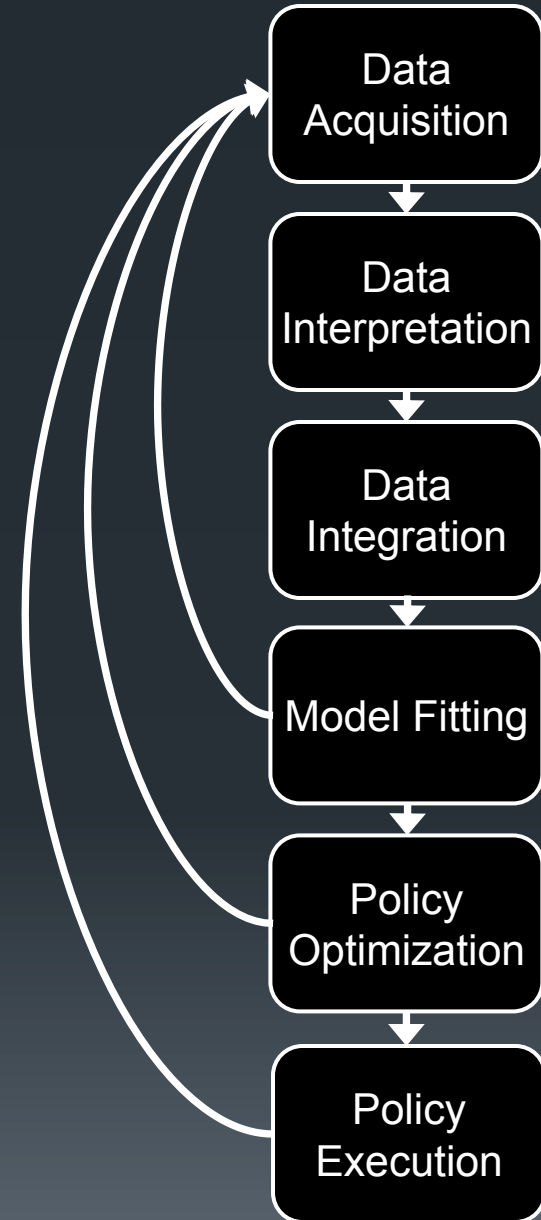


Disregarding costs
to fishing industry

Full consideration of costs
to fishing industry

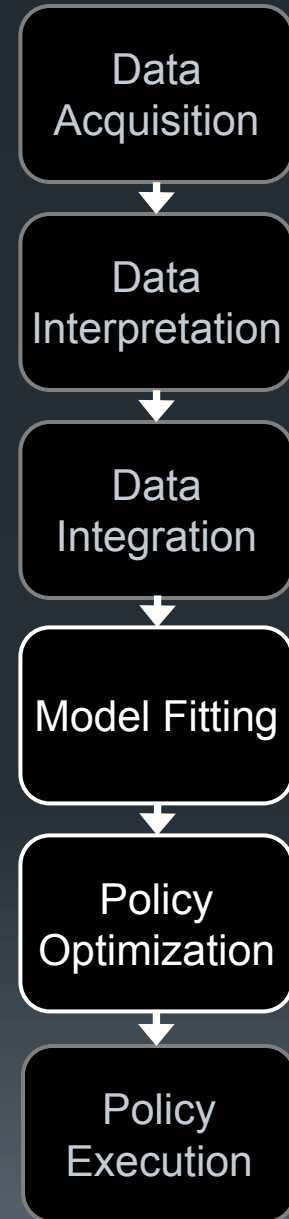
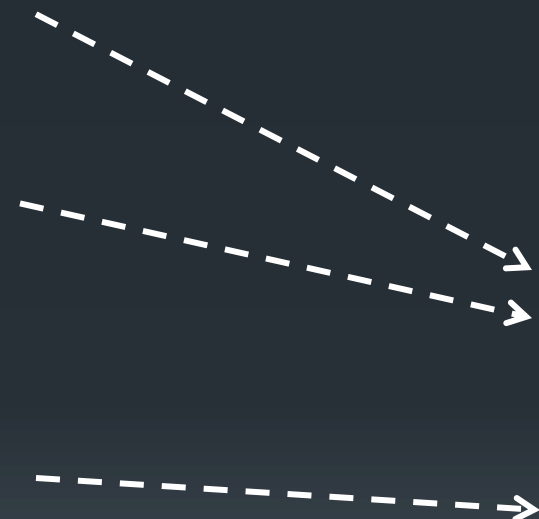
Policy Execution

- Repeat
 - Observe Current State
 - Choose and Execute Action
- Need to continually improve our models and update our policies
- Challenge: We must start taking actions while our models are still very poor.
 - How can we make our models robust to both the “known unknowns” (our known uncertainty) and the “unknown unknowns” (things we will discover in the future)



Drill Down: Three Projects at Oregon State

- Species Distribution Modeling with Imperfect Observations
 - Explicit Observation Models
 - Flexible Latent Variable Models
- Models of Bird Migration
 - Collective Graphical Models
- Policy Optimization
 - Controlling Invasive Species
 - Algorithms for Large Spatial MDPs



Project eBird

www.ebird.org



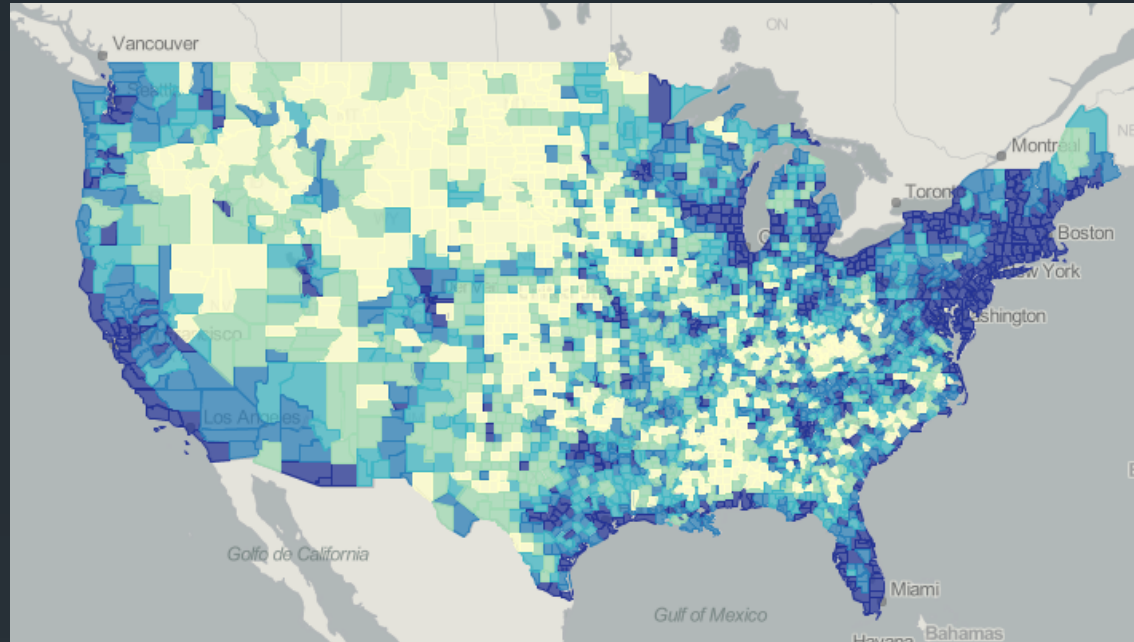
- Volunteer Bird Watchers
 - Stationary Count
 - Travelling Count
- Time, place, duration, distance travelled
- Species seen
 - Number of birds for each species or 'X' which means ≥ 1
- Checkbox: This is everything that I saw

- 8,000-12,000 checklists per day uploaded



Species Distribution Modeling from Citizen Science Data:

- eBird data issues
 - imperfect detection
 - variable expertise
 - sampling bias
 - ...

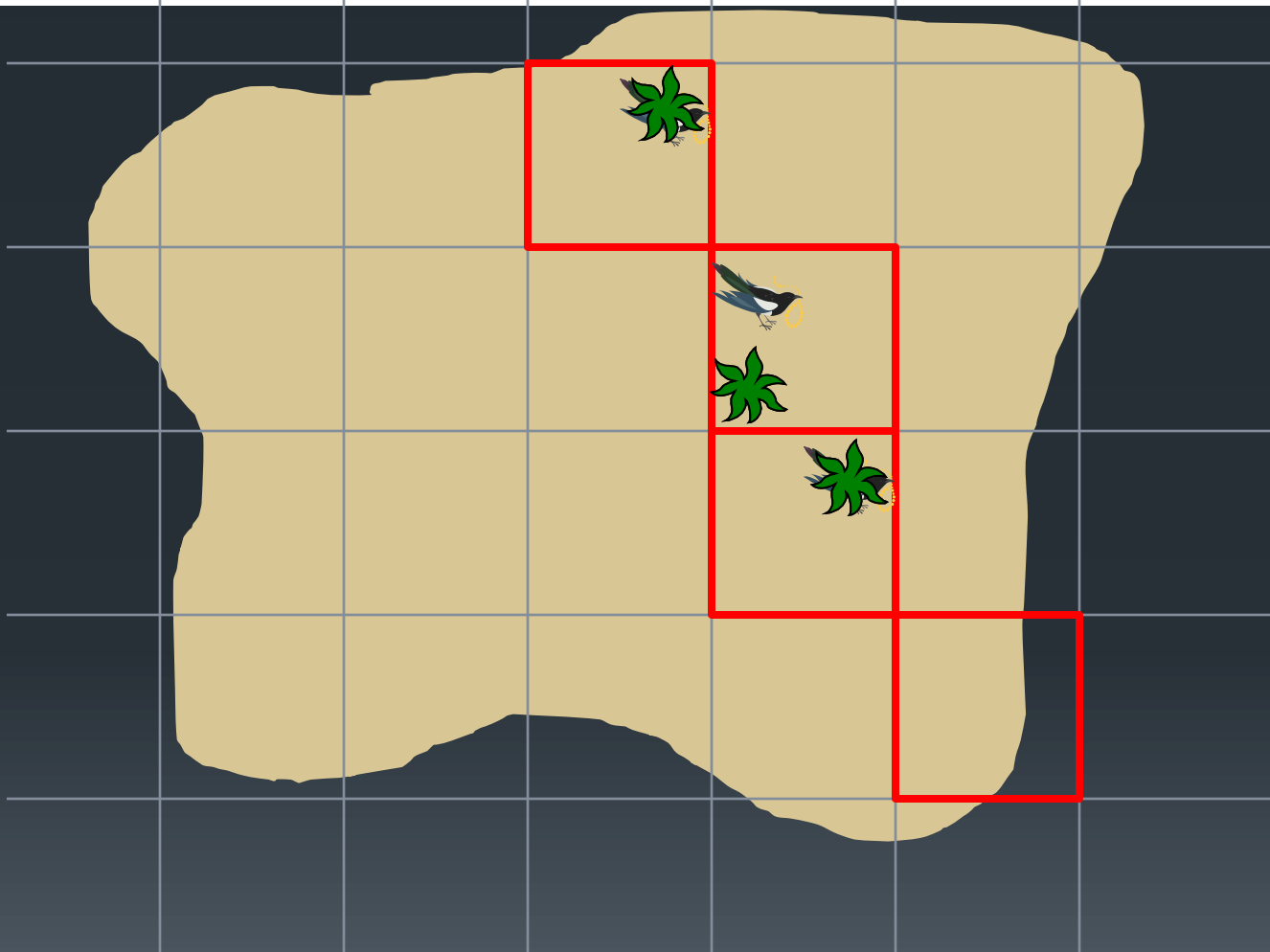


Tom Auer <http://geocommons.com/maps/137230>



Imperfect Detection

Partial Problem: Some birds are hidden but birds hide on different visits



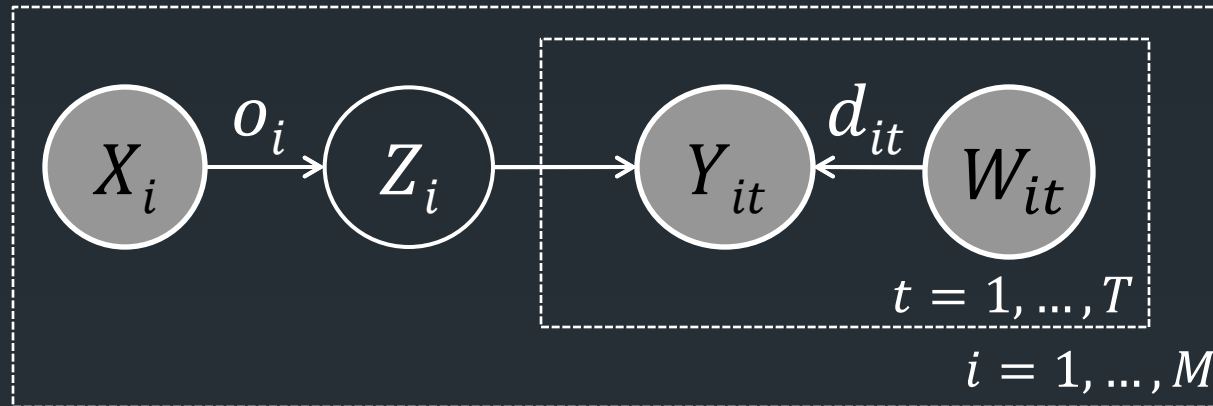
Multiple Visits to the Same Sites



		Detection History		
Site	<i>True occupancy (latent)</i>	Visit 1 (rainy day, 12pm)	Visit 2 (clear day, 6am)	Visit 3 (clear day, 9am)
A (forest, elev=400m)	1	0	1	1
B (forest, elev=500m)	1	0	1	0
C (forest, elev=300m)	1	0	0	0
D (grassland, elev=200m)	0	0	0	0

Occupancy-Detection Model

Mackenzie, et al, 2002



$Z_i \sim P(Z_i | X_i)$: Species Distribution Model

$$P(Z_i = 1 | X_i) = o_i = F(X_i) \text{ "occupancy probability"}$$

$Y_{it} \sim P(Y_{it} | Z_i, W_{it})$: Observation model

$$P(Y_{it} = 1 | Z_i, W_{it}) = Z_i d_{it}$$

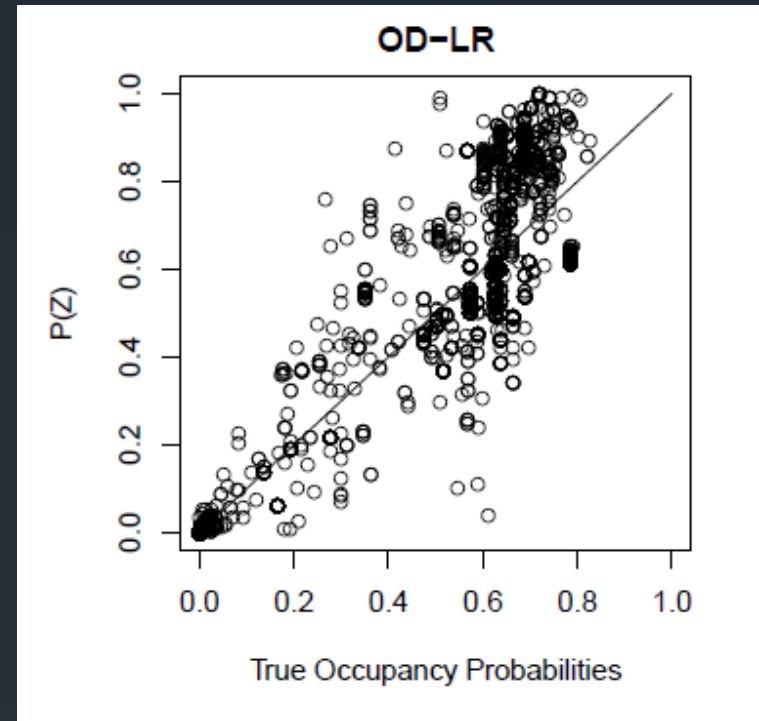
$$d_{it} = G(W_{it}) \text{ "detection probability"}$$

Standard Approach: Log Linear (logistic regression) models

- $\log \frac{F(X_i)}{1-F(X_i)} = \beta_0 + \beta_1 X_{i1} + \dots + \beta_J X_{iJ}$
- $\log \frac{G(W_{it})}{1-G(W_{it})} = \alpha_0 + \alpha_1 W_{it1} + \dots + \alpha_K W_{itK}$
- Fit via maximum likelihood

Results on Synthetic Species with Nonlinear Dependencies

- Predictions exhibit high variance because model cannot fit the nonlinearities well

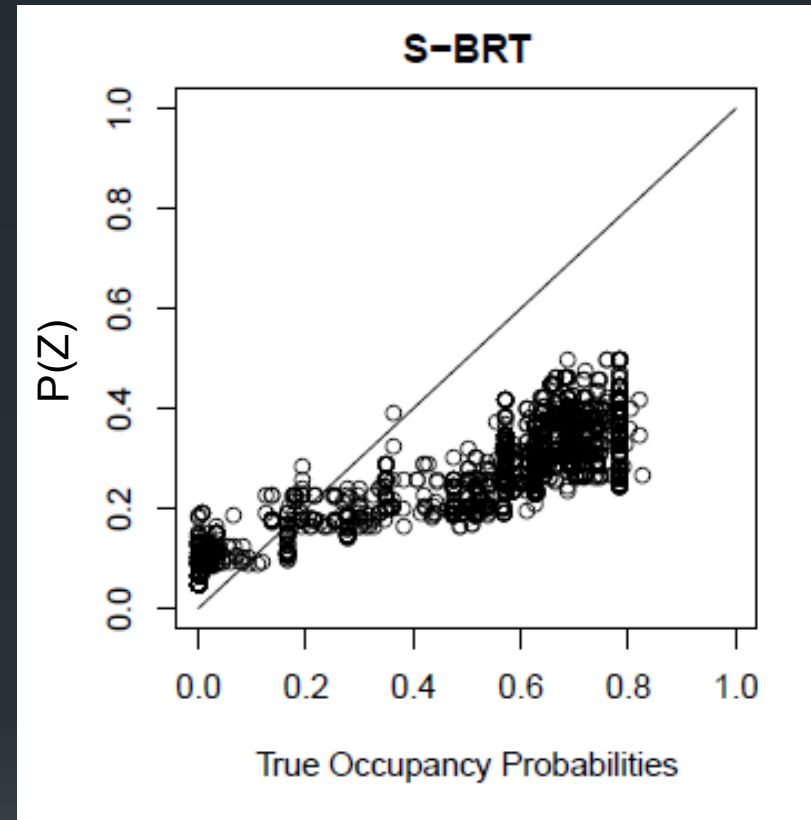


A Flexible Predictive (non-Latent) Model

- Predict the observation y_{it} from the combination of occupancy covariates x_i and detection covariates w_{it}
- Boosted Regression trees
 - $\log \frac{P(Y_{it}=1|X_i, W_{it})}{P(Y_{it}=0|X_i, W_{it})} = \beta_1 tree_1(X_i, W_{it}) + \dots + \beta_L tree_L(X_i, W_{it})$
 - Fitted via functional gradient descent (Friedman, 2001, 2010)
- Model complexity is tuned to the complexity of the data
 - Number of trees
 - Depth of each tree

Predictive Model Results

- Systematically biased because it does not capture the latent occupancy
 - Underestimates occupancy at occupied sites to fit detection failures
- Much lower variance than the Occupancy-Detection model, because it can handle the non-linearities



Two Approaches: Summary

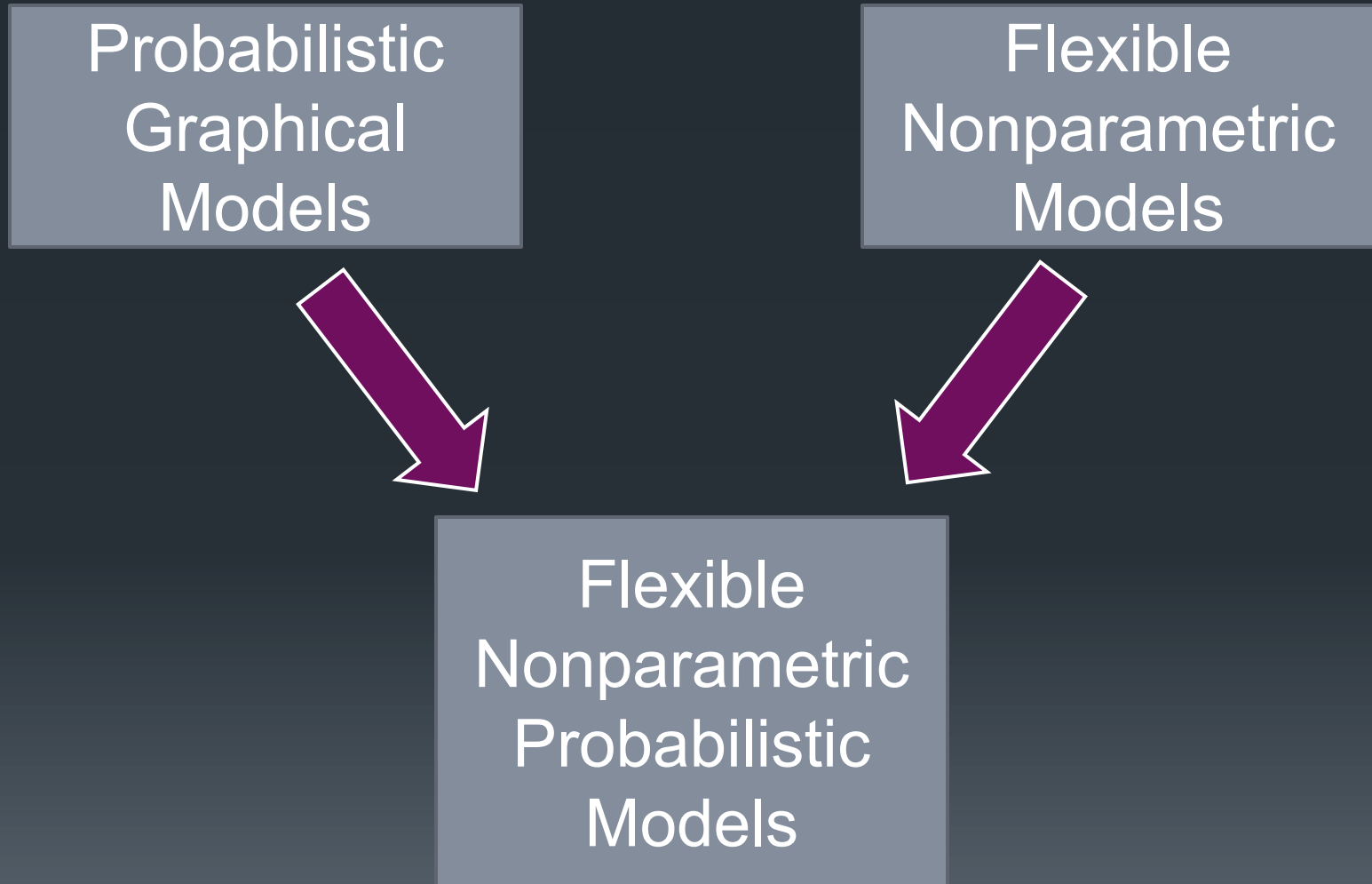
Probabilistic Graphical Models

- Advantages
 - Supports latent variables
- Disadvantages
 - Hard to use
 - Model must be carefully designed
 - Data must be transformed to match model assumptions
 - Model has fixed complexity so either under-fits or over-fits

Flexible Nonparametric Models

- Advantages
 - Model complexity adapts to data complexity
 - Easy to use “off-the-shelf”
- Disadvantages
 - Do not support latent variables

The Dream



A Simple Idea:

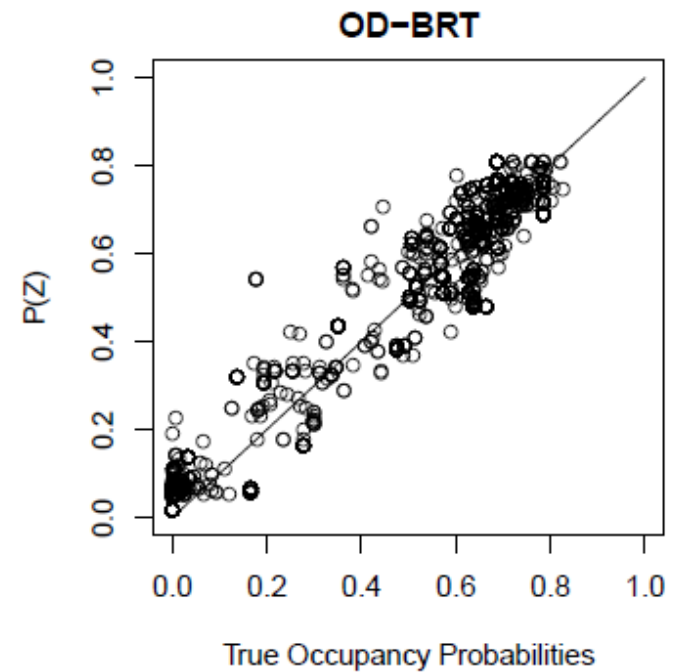
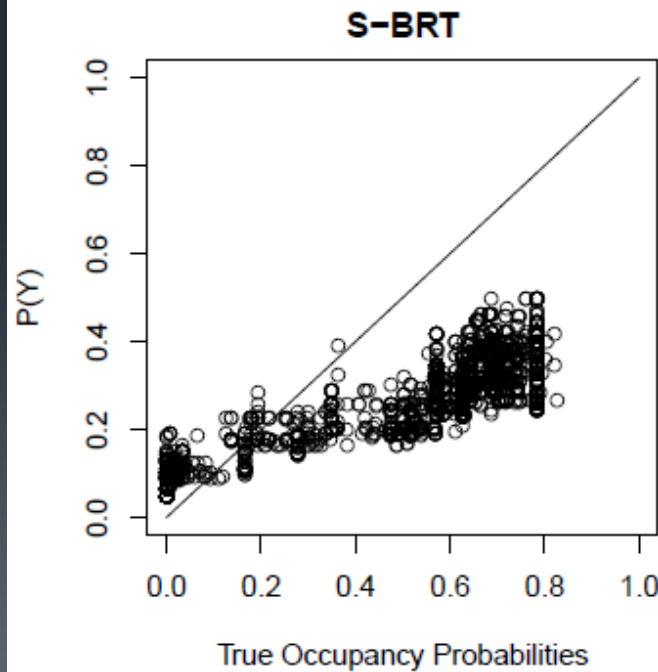
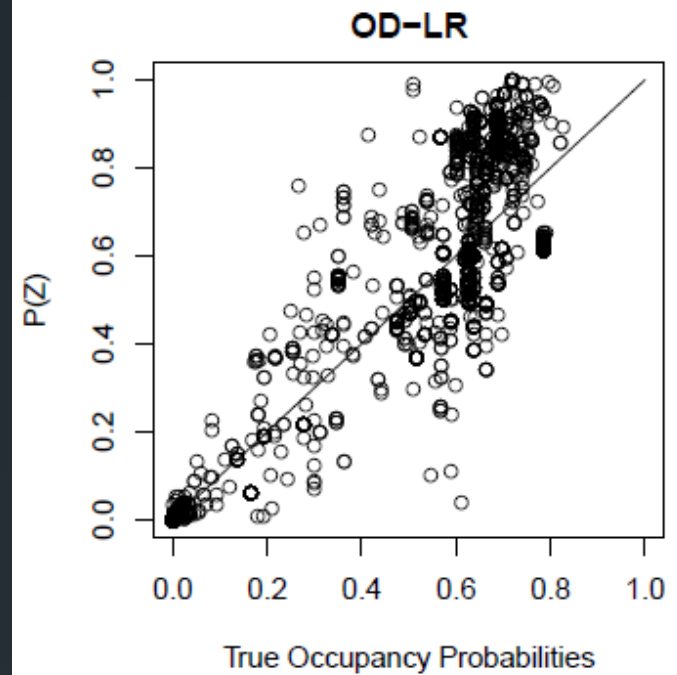
Parameterize F and G as boosted trees

- $\log \frac{F(X)}{1-F(X)} = f^0(X) + \rho_1 f^1(X) + \dots + \rho_L f^L(X)$
- $\log \frac{G(W)}{1-G(W)} = g^0(W) + \eta_1 g^1(W) + \dots + \eta_L g^L(W)$
- Perform functional gradient descent in F and G
- See also...
 - Kernel logistic regression
 - Non-parametric Bayes
 - RKHS embeddings of probability distributions

Results: OD-BRT

(Hutchinson, Liu & Dietterich, AAI 2010)

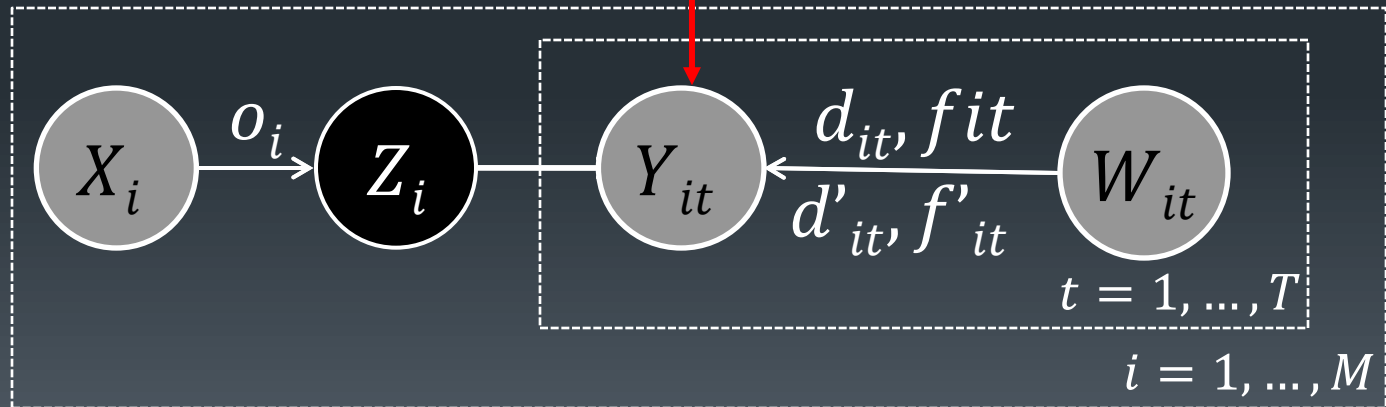
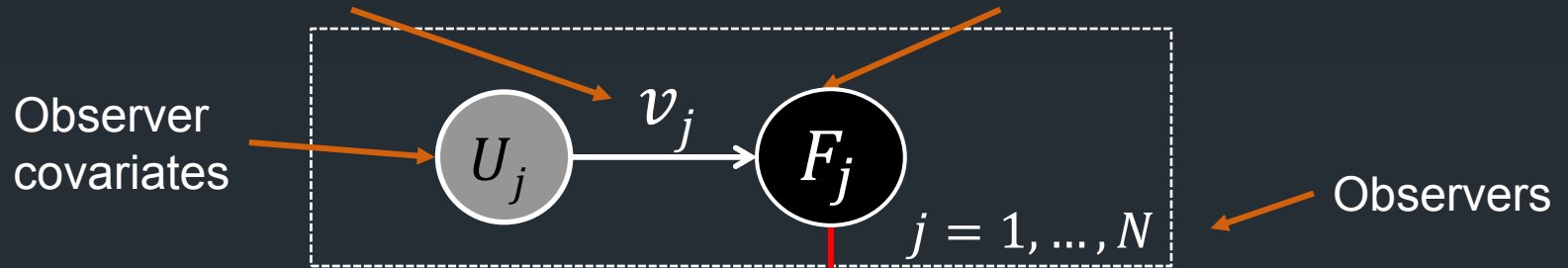
- Occupancy probabilities are predicted very well



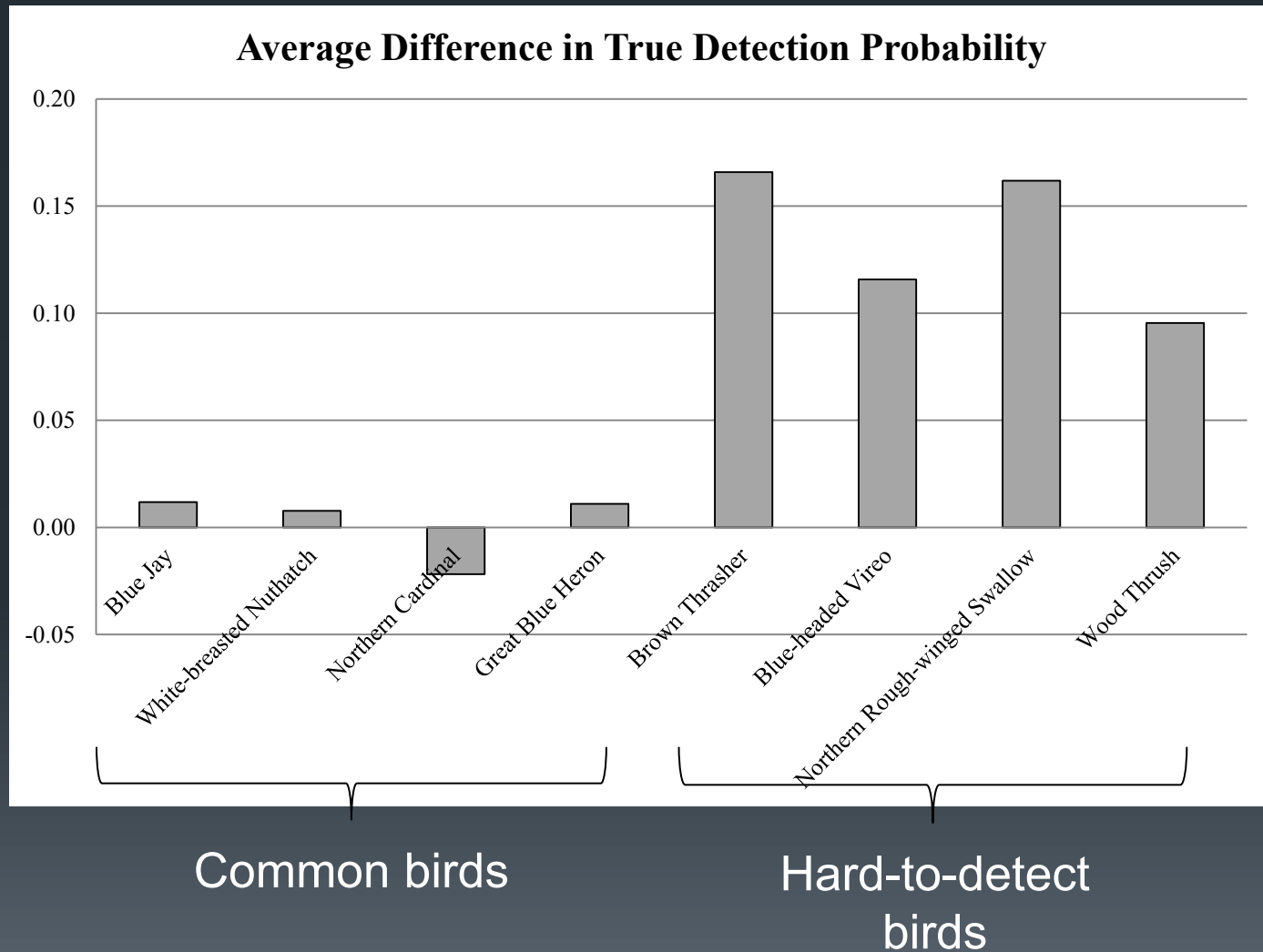
Handling Variable Expertise



Expertise probability (function of U) Expert/novice observer

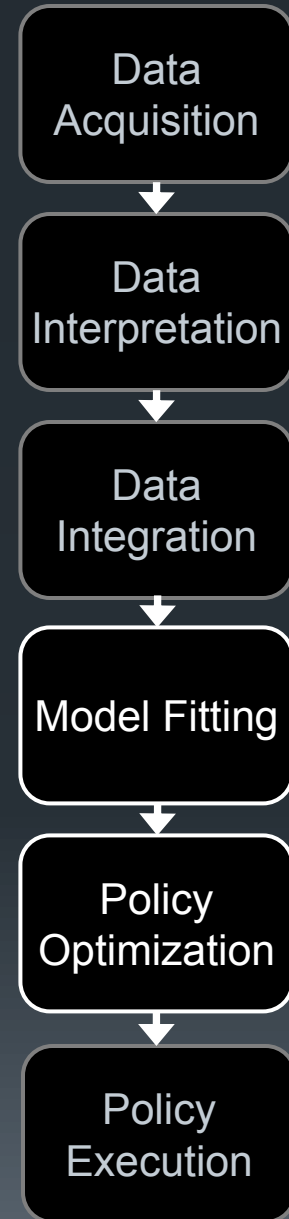


Expert vs. Novice Differences



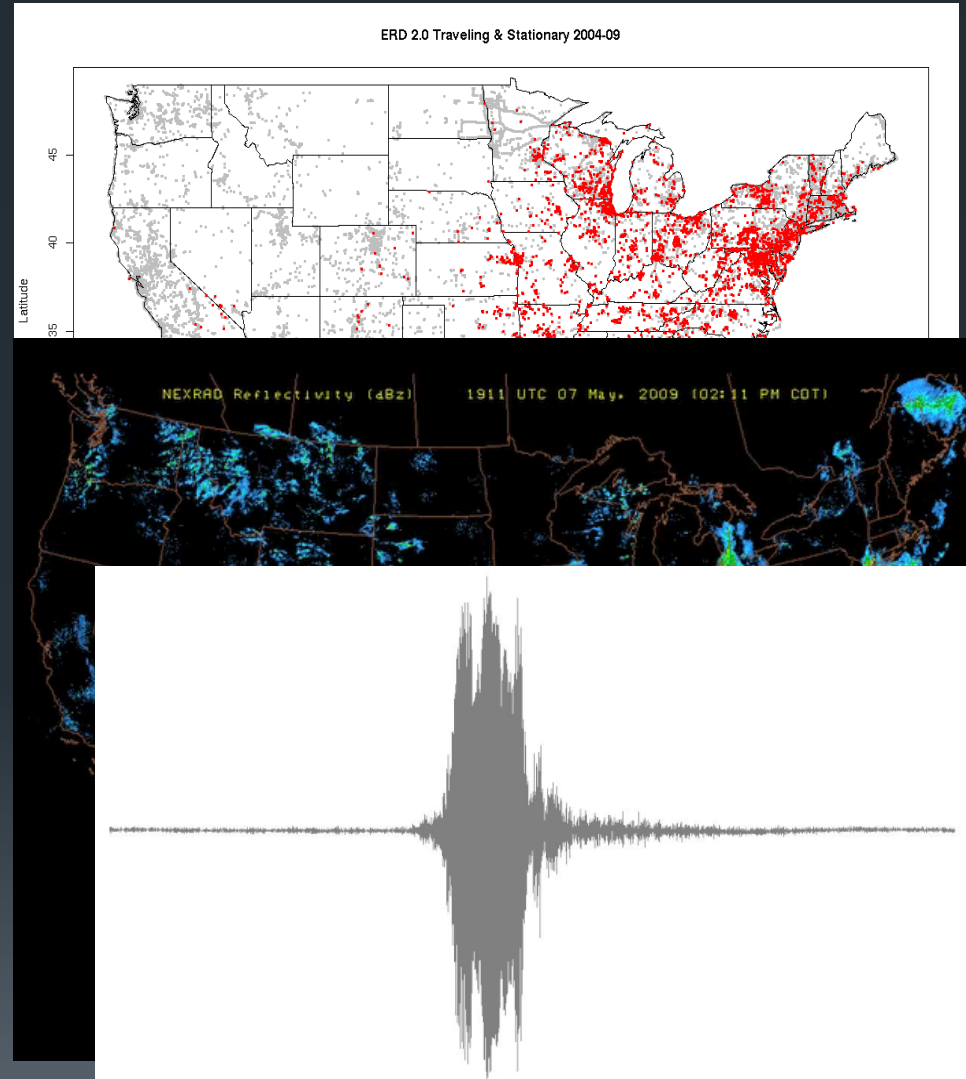
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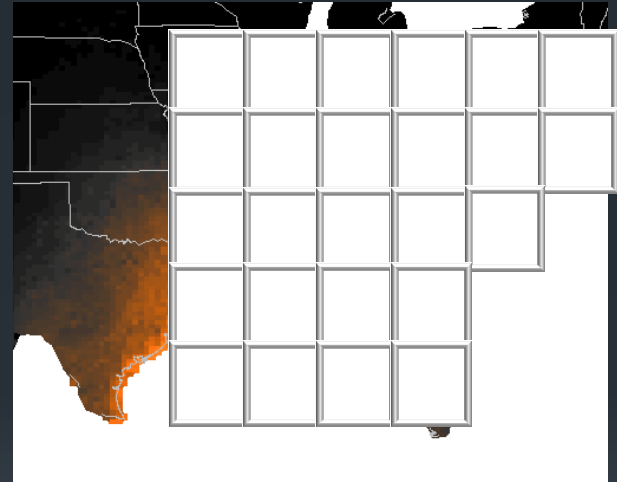
BirdCast: Understanding and Forecasting Bird Migration

- Available data:
 - eBird observations
 - NEXRAD weather radar
 - acoustic monitoring stations
 - weather data
 - weather forecast
- Goals:
 - predict spatial distribution of each species 24- and 48-hours in advance
 - understand what factors drive bird migration
 - wind speed and direction?
 - temperature?
 - relative humidity?
 - absolute or relative timing?
 - food availability?



Modeling Goal: Spatial Hidden Markov Model

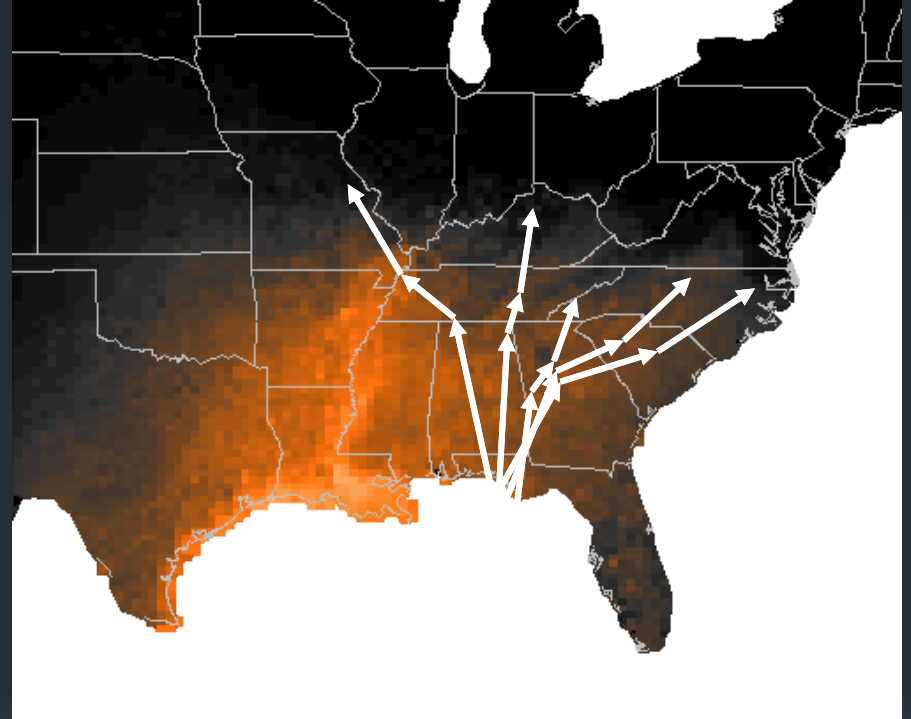
- Define a grid over the US
- Let n_i^t be the number of birds in cell i at time t
- Learn a probability transition matrix that depends on the features
 - wind, temperature, time, etc.



Problem:

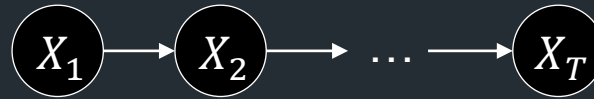
We have only aggregate data

- The data we wish we had:
 - tracks of individual birds
- The data we have:
 - ebird: aggregate counts of anonymous birds
 - radar: birds per km³ summed over all species
 - ...

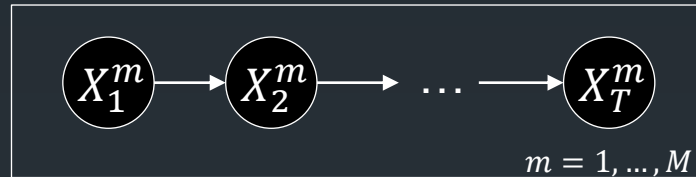


Solution: Collective Graphical Models

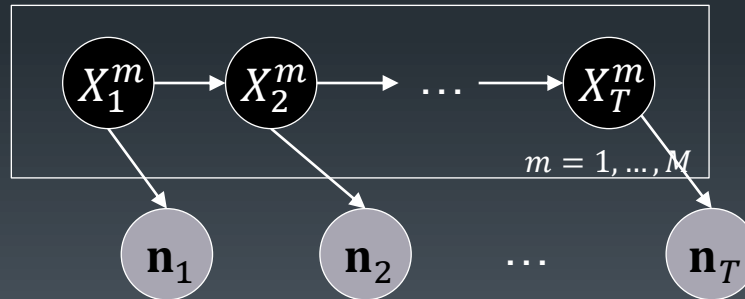
Individual model:
Markov chain on grid
cells



Population model:
iid copies of individual
model



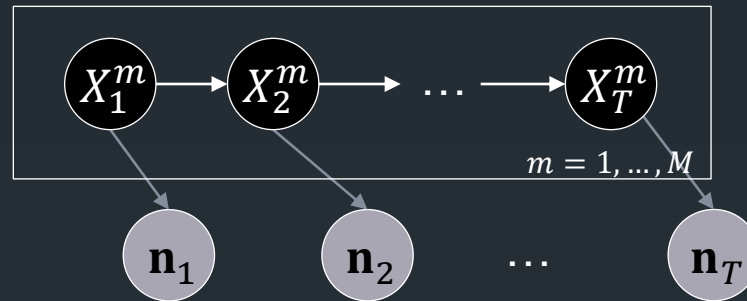
Derive aggregate
observations



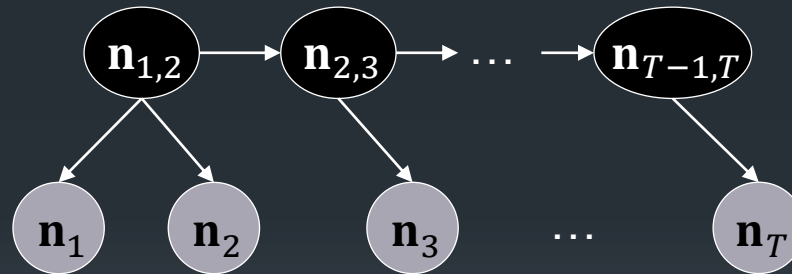
Solution:

Collective Graphical Models (2)

Derive aggregate observations



Marginalize out individuals:
chain-structured model on
sufficient statistics



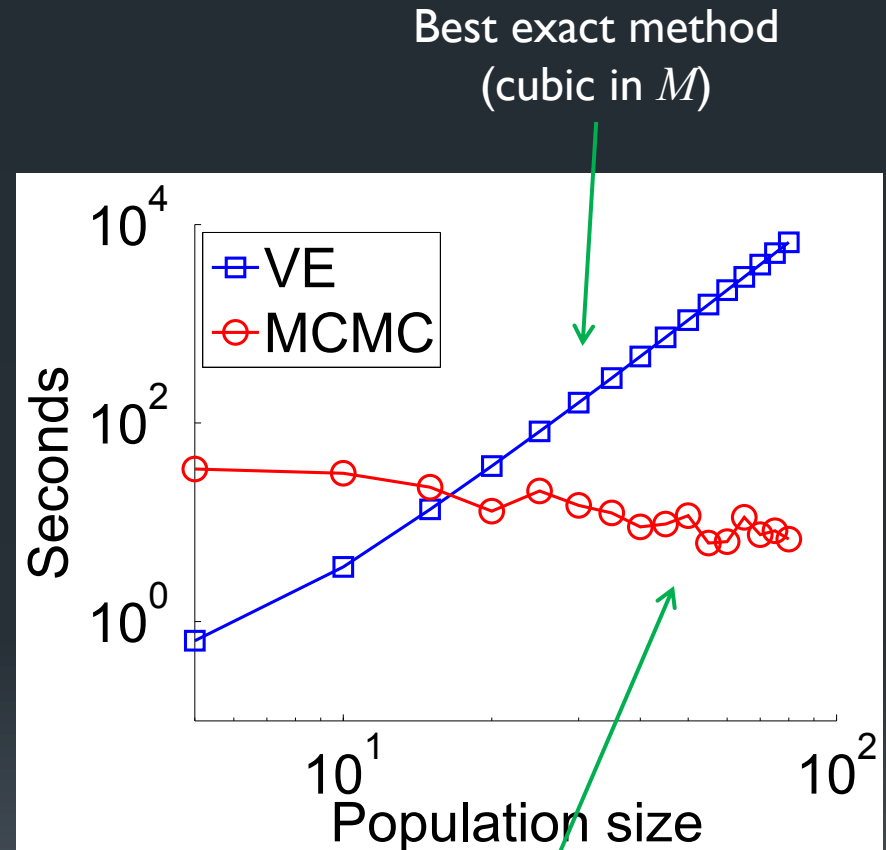
Transition counts

Note: MAP estimates of n_{ij} are sufficient statistics of the individual model
We don't need to reconstruct individual tracks to fit the individual model

Inference in Collective Graphical Models

(Sheldon & Dietterich, NIPS 2011)

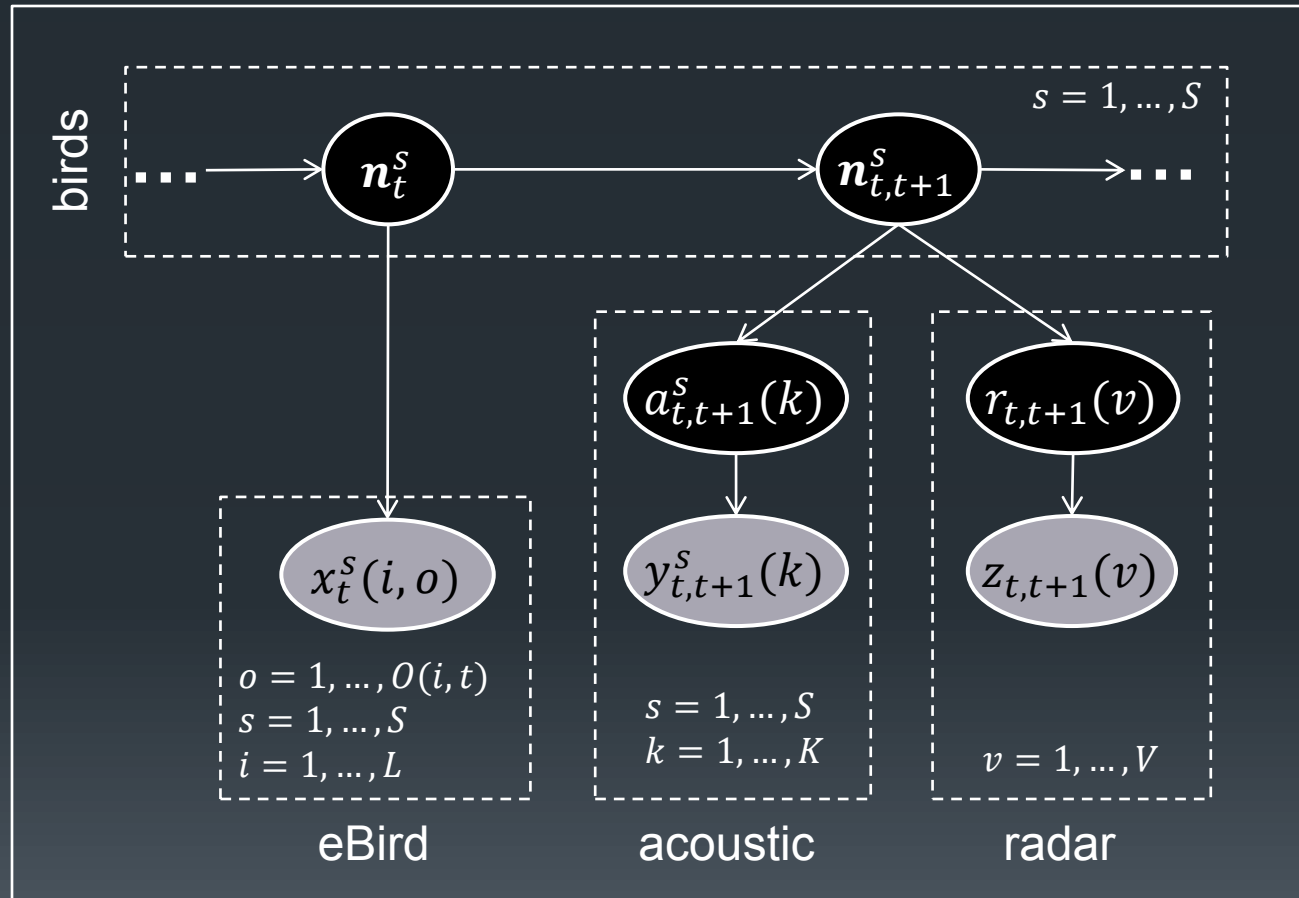
- Model Fitting via EM
 - Requires sampling from $P(\mathbf{n}_{t,t+1} | \mathbf{n}_1, \dots, \mathbf{n}_T)$
 - posterior distribution of “flows” through the HMM trellis
- Fast Gibbs Sampler that respects Kirchoff’s laws
 - running time is independent of population size



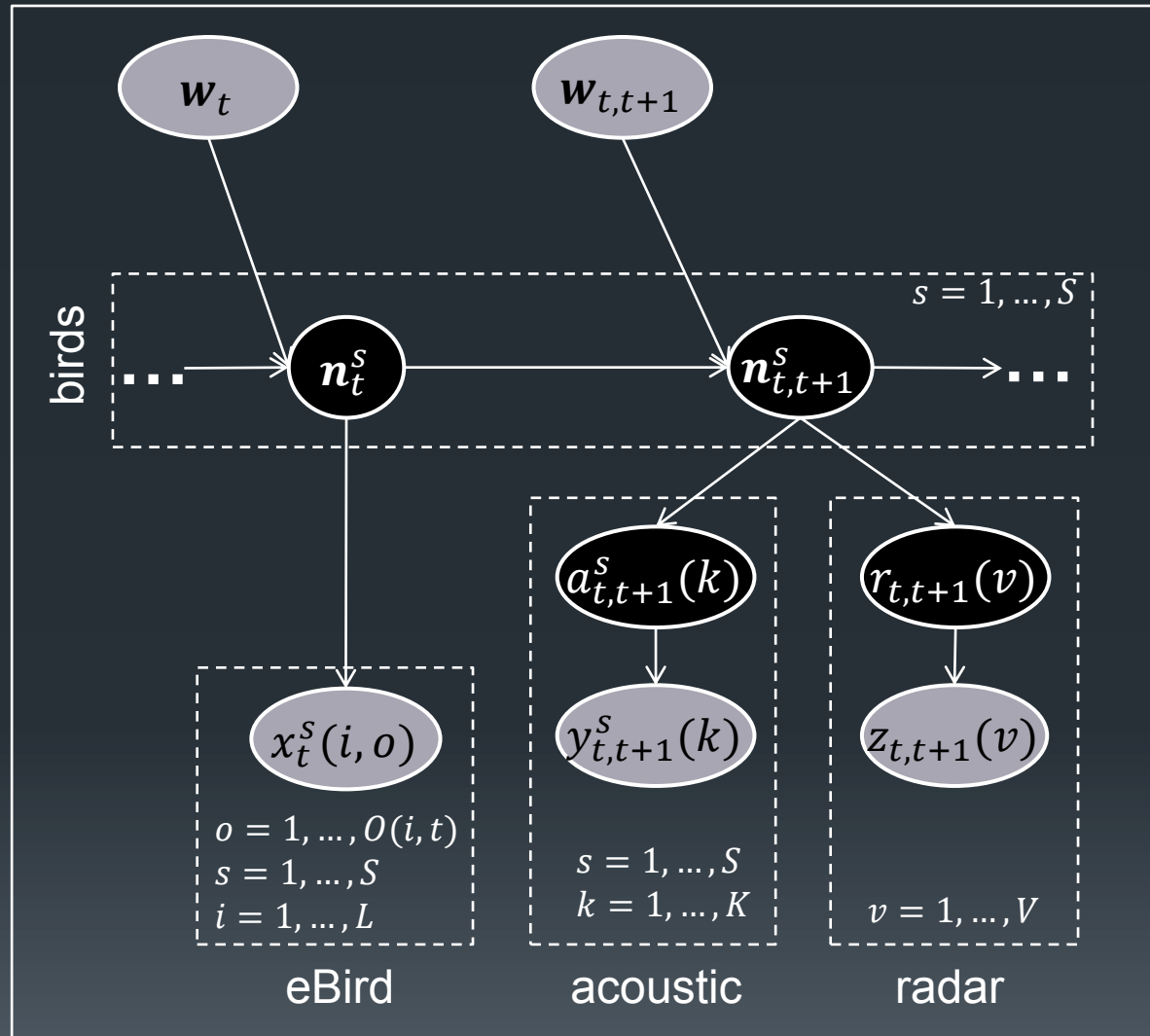
Our method
(to 2% relative error)

The Migration Model

- Species s
- Observers o
- Sites i
- Acoustic stations k
- Radar sites v

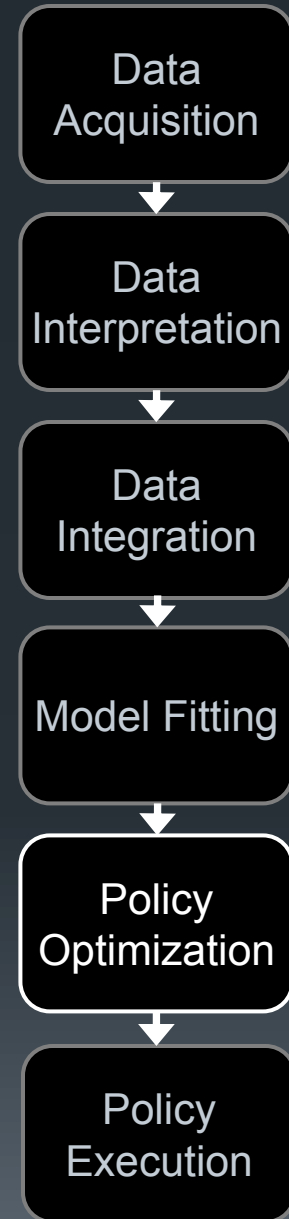


With Added Covariates



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 - Algorithms for simulator-defined MDPs



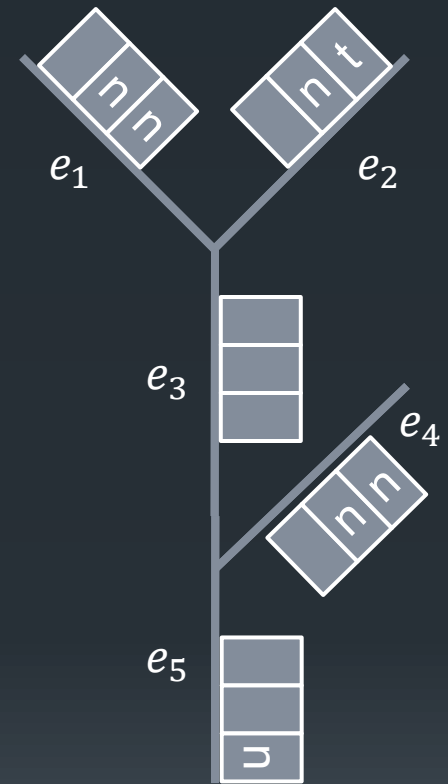
Invasive Species Management in River Networks

- Tamarisk: invasive tree from the Middle East
 - Out-competes native vegetation for water
 - Reduces biodiversity
- What is the best way to manage a spatially-spreading organism?



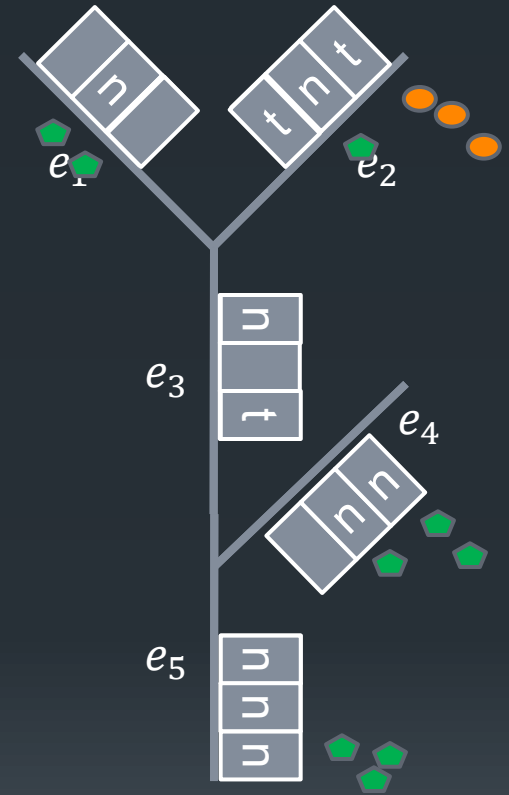
Markov Decision Process

- Tree-structured river network
 - Each edge $e \in E$ has H “sites” where a tree can grow.
 - Each site can be
 - {empty, occupied by native, occupied by invasive}
 - # of states is 3^{EH}
- Management actions
 - Each edge: {do nothing, eradicate, restore, eradicate+restore}
 - # of actions is 4^E



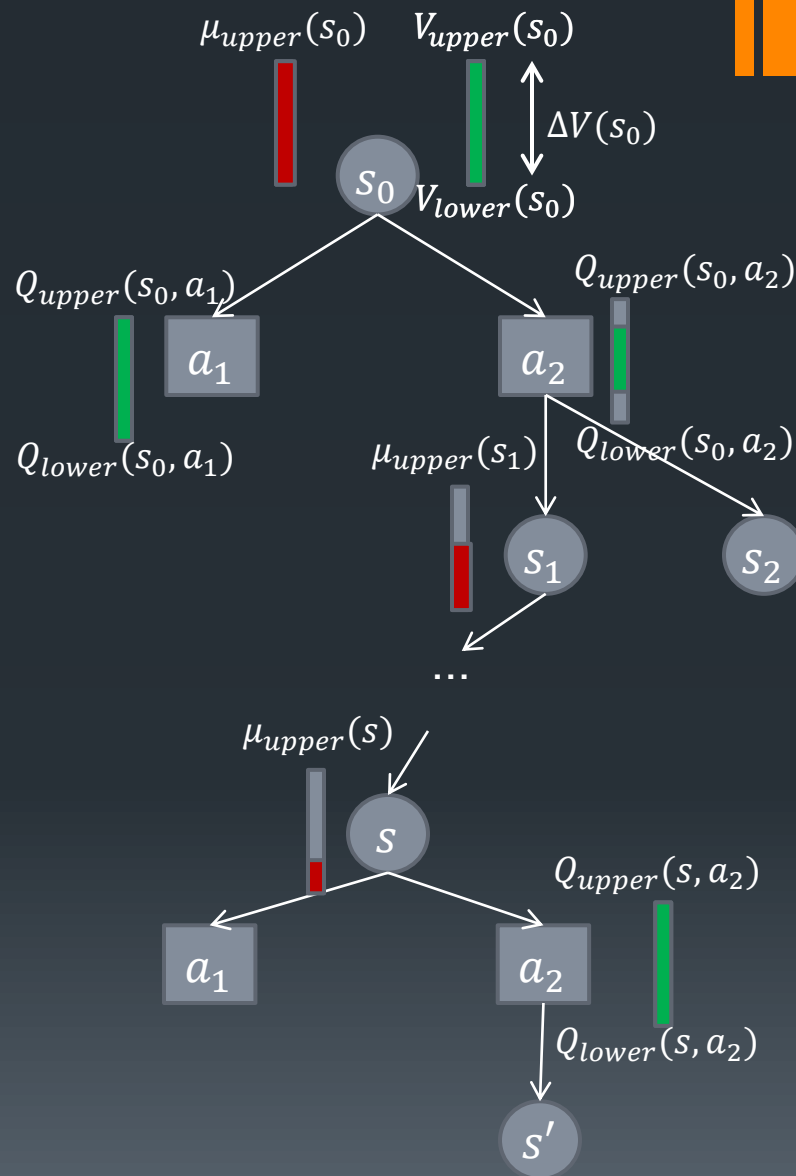
Dynamics and Objective

- Dynamics:
 - In each time period
 - Natural death
 - Seed production
 - Seed dispersal (preferentially downstream)
 - Seed competition to become established
 - Couples all edges because of spatial spread
 - Inference is intractable
- Objective:
 - Minimize expected discounted costs (sum of cost of invasion plus cost of management)
 - Subject to annual budget constraint



Algorithm DDV

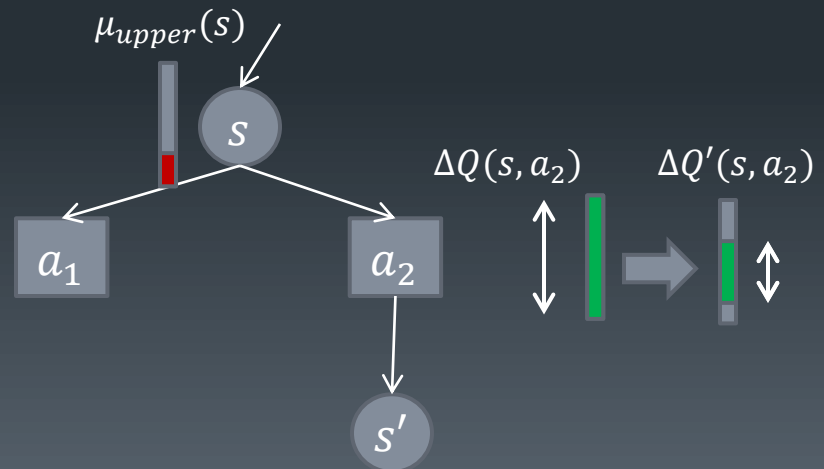
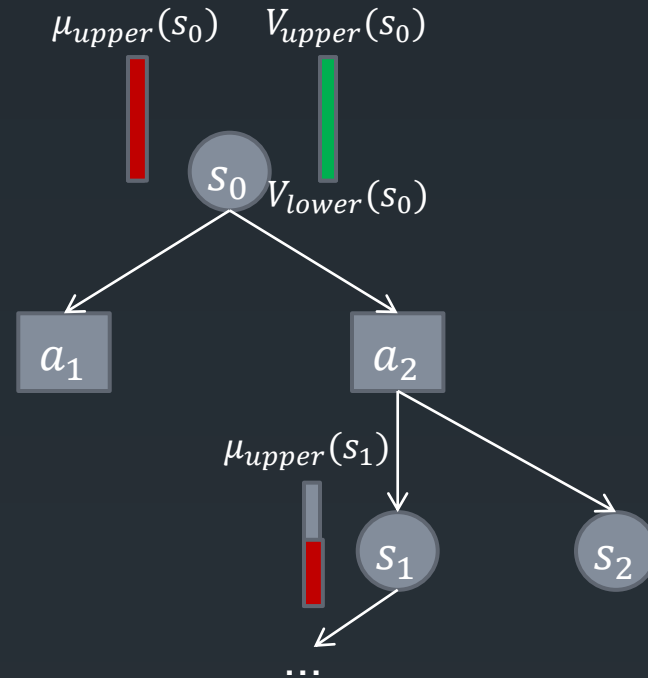
- Goal: Compute PAC-optimal policy while minimizing simulator calls
- Explicit representation of the MDP (Transition matrix and Q table)
- Confidence intervals $Q_{lower}(s, a)$ and $Q_{upper}(s, a)$
- Confidence interval on $V(s_0)$
- Upper bound on discounted state occupancy probability $\mu_{upper}(s)$
 - $\mu^\pi(s) = \sum_t \gamma^t P(s^t = s | s^0 = s_0, \pi)$
- Measure of uncertainty:
 - $\Delta V(s_0) = V_{upper}(s_0) - V_{lower}(s_0)$



Algorithm DDV

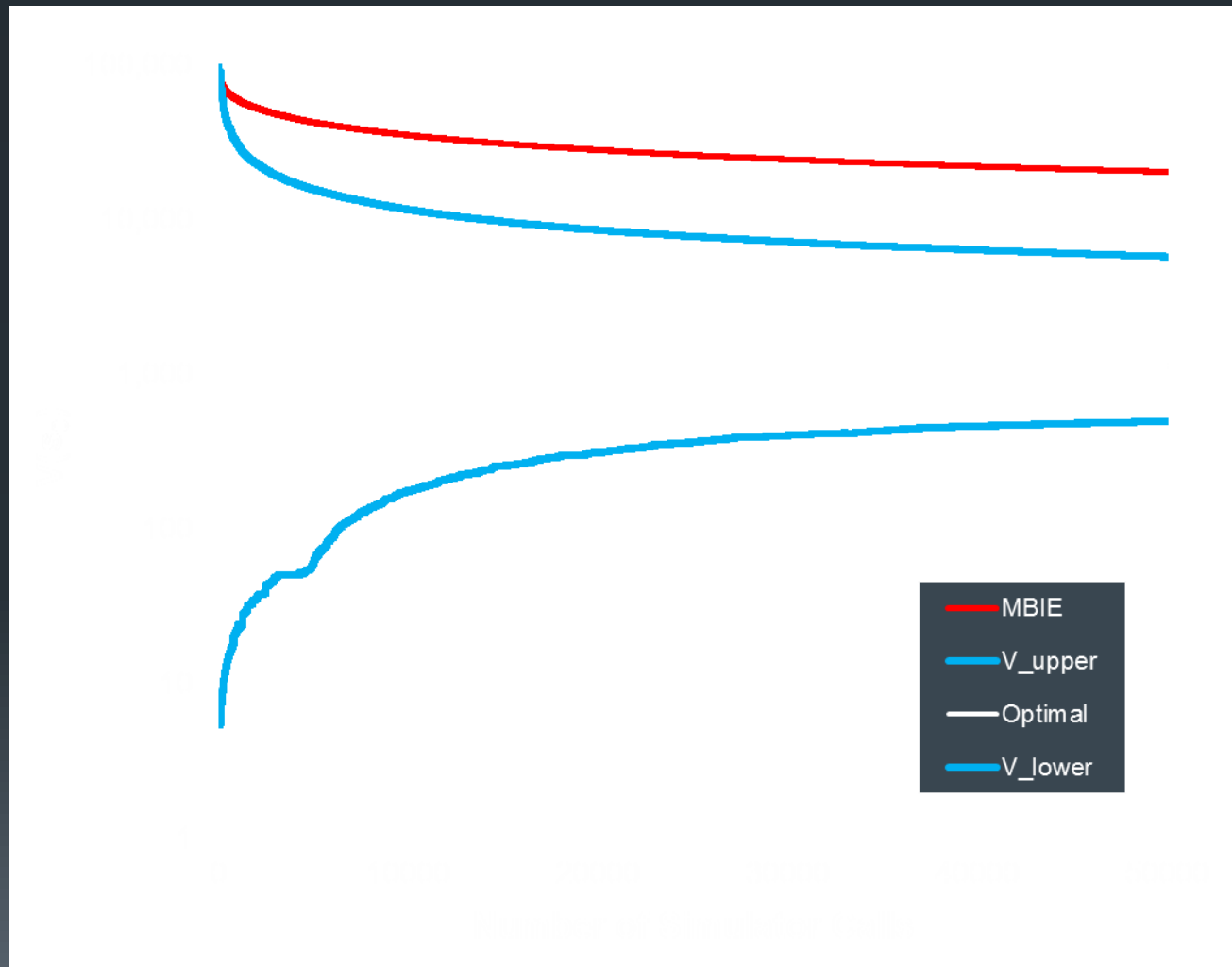
- Exploration heuristic:
 - Exploring (s, a_2) will cause a local reduction in $\Delta V(s_0)$

$$\Delta Q(s, a_2) = Q_{upper}(s, a_2) - Q_{lower}(s, a_2)$$
 - The impact of this on $\Delta V(s_0)$ can be approximated by $\mu_{upper}(s)[\Delta Q(s, a_1) - \Delta Q'(s, a_1)]$
 - Explore the (s, a) that maximizes $\mu_{upper}(s)[\Delta Q(s, a) - \Delta Q'(s, a)]$



Results on “RiverSwim” benchmark

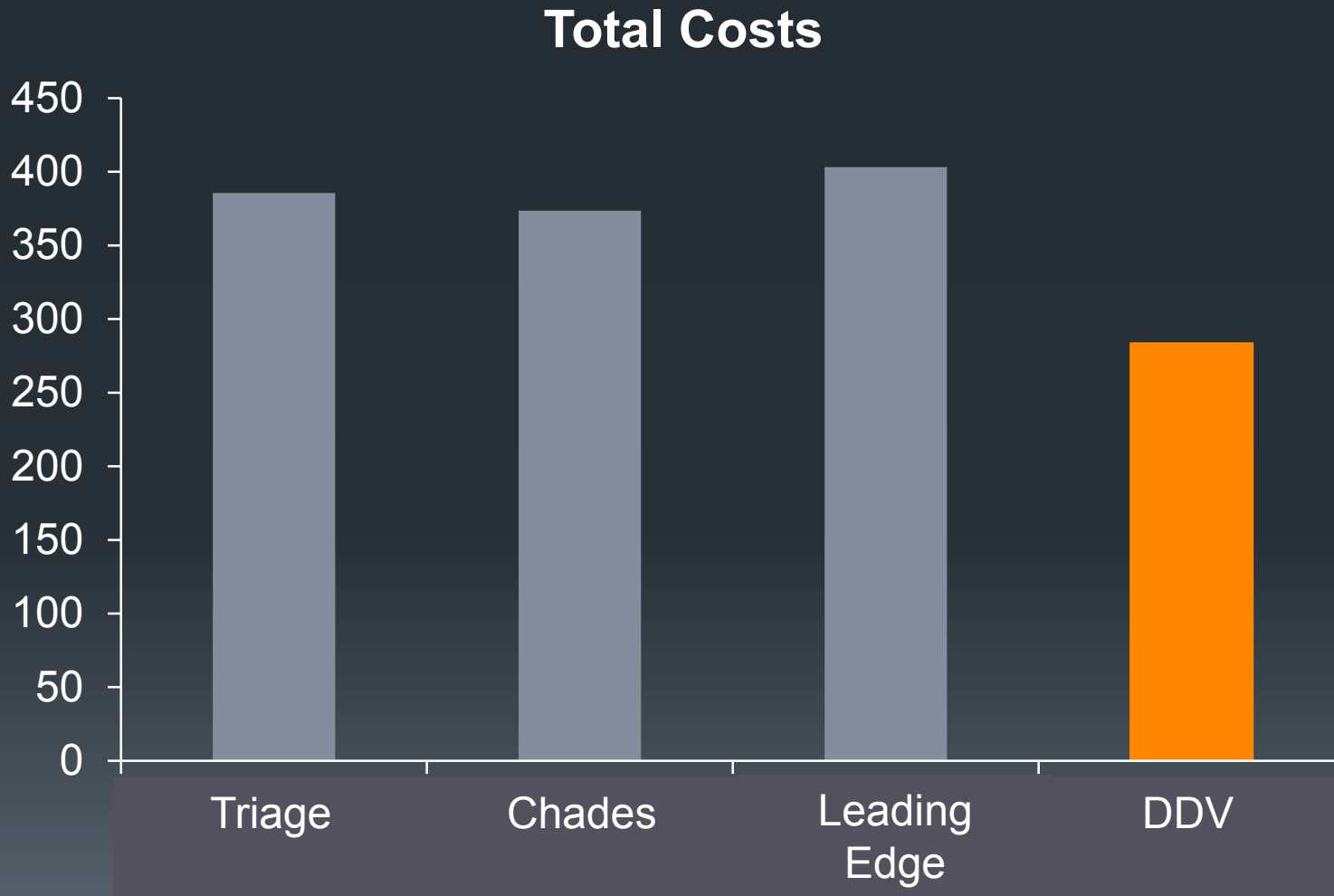
- Comparison with Strehl & Littman (2008) Model-Based Interval Estimation (MBIE)
- DDV reduces the uncertainty in $V(s_0)$ much faster than MBIE
 - note log scale
- Both algorithms have PAC guarantees



Published Rule of Thumb Policies for Invasive Species Management

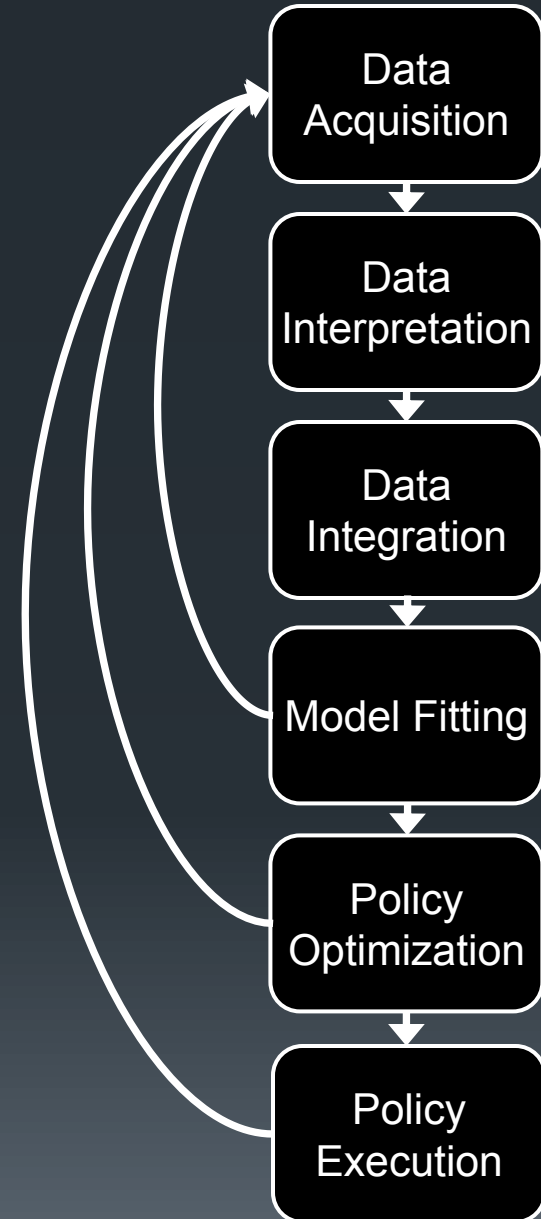
- Triage Policy
 - Treat most-invaded edge first
 - Break ties by treating upstream first
- Leading edge
 - Eradicate along the leading edge of invasion
- Chades, et al.
 - Treat most-upstream invaded edge first
 - Break ties by amount of invasion
- DDV
 - Our PAC solution

Cost Comparisons: Rule of Thumb Policies vs. DDV



Summary

- Data → Models → Policies
- Three projects at Oregon State:
 - Species Distribution Modeling with Imperfect Observations
 - Flexible Latent Variable Models
 - Models of Bird Migration
 - Collective Graphical Models
 - Policy Optimization
 - Algorithms for simulator-defined MDPs



Distinctive Characteristics of Sustainability Problems

- Goal is typically to encourage or prevent spatial spread
 - Encourage spread of endangered species
 - Manage spread of fire
 - Prevent spread of diseases and invasive species
 - Over long time horizons
 - Resulting MDPs are immense
 - Dynamics are typically available only via a simulator
- Data are extremely noisy, heterogeneous, and incomplete
 - Need to learn latent process dynamical models from this data
- Optimization is based on learned models
 - Need to be robust to incorrect models
 - Need to be robust to the unknown unknowns
 - Risk sensitive:
 - avoid species extinctions
 - avoid catastrophic fires

Computational Sustainability

- There are many opportunities for computing to contribute to sustainable ecosystem management
- There are many challenging machine learning research problems to be solved
- Institute for Computational Sustainability:
<http://www.computational-sustainability.org/>

Thank-you

- Rebecca Hutchinson, Liping Liu: Boosted Regression Trees in OD models
- Dan Sheldon: Collective Graphical Models
- Steve Kelling, Andrew Farnsworth, Wes Hochachka, Daniel Fink: BirdCast
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Questions?